NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)



Affiliated to

DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY UTTAR PRADESH, LUCKNOW



Evaluation Scheme & Syllabus

For

Master of Technology Mechanical Engineering

First Year

(Effective from the Session: 2022-23)

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Master of Technology Mechanical Engineering <u>EVALUATION SCHEME</u> SEMESTER -1

| S. N | Course Code | Subject | Р | eriod | ls | Eva | luatio | on Sche | emes | - | and Sester | Total | Credit |
|---------|----------------|--|-----------|---------|-------|--------|--|-----------|--------|-------|---------------|-------------|------------|
| | | Theory | L | Т | Р | C T | T A | Tot al | PS | ТЕ | PE | | |
| 1 | AMTME0101 | Simulation Modelling and Analysis | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 2 | AMTME0102 | Design of Experiments | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 3 | AMTCC0101 | Research Process and Methodology | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 4 | | Departmental Elective – I | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 5 | | Departmental Elective – II | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 6 | AMTME0151 | simulation Modelling and Analysis lab | 0 | 0 | 4 | - | - | | 20 | - | 30 | 50 | 2 |
| 7 | AMTME0152 | Industry 4.0 Lab | 0 | 0 | 4 | - | - | | 20 | - | 30 | 50 | 2 |
| | | Total | 15 | 0 | 8 | - | - | | - | - | - | 600 | 19 |
| | | | | | | | | | | | | | |
| | | | AMTME | | E0111 | | Geometric Design & Rapid Prototyping | | | | | | typing |
| | | | AN | AMTME01 | | 12 | | Ac | lvanc | ed He | at & Ma | ass Trans | fer |
| | Departmo | ental Elective-I | AN | итм | E01 | 13 | | | Rene | wable | Energ | y System | |
| | | | AMTME0114 | | | | Reliability, Maintenance Management & safety | | | | | | t & safety |
| | | | | | | | | | | | | | |
| | | | AN | ИТМ | E01 | 15 | | | | Turbo | Mach | ines | |
| | | | AN | ИТМ | E01 | 16 | | Ad | lvanco | ed Me | chanic | al Vibratic | ons |
| | Departme | ental Elective-II | AN | ИТМ | E01 | 17 | Operations Research | | | | | | |
| | | | AN | ИТМ | E01 | 18 | | | Ad | vance | d I.C. E | Ingines | |

Abbreviation Used:-

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., PE: Practical End Semester Exam.

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Master of Technology Mechanical Engineering <u>EVALUATION SCHEME</u> SEMESTER -II

| S. N | Course Code | | Subject | | Period | ls | Eva | aluati | ion Scl | neme | | nd nester | Total | Credit |
|---------|------------------|------------------------------------|--|---------------|------------------------------|----------|----------|--------------|-----------------|------------------|------------------|-------------------------------------|------------|--------|
| | | Theory | | L | Т | Р | C T | T A | Tot al | PS | ТЕ | PE | Total | |
| 1 | AMTME0201 | Digital Ma Automation | nufacturing and n | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 2 | AMTME0202 | Composite | Materials | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 3 | | Departmen | Departmental Elective-III | | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 4 | | Departmental Elective-IV | | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 5 | | Departmental Elective-V | | 3 | 0 | 0 | 20 | 10 | 30 | - | 70 | - | 100 | 3 |
| 6 | AMTME0251 | Automation and Mechatronics Lab | | 0 | 0 | 4 | - | - | - | 20 | - | 30 | 50 | 2 |
| 7 | AMTME0252 | Composite | Materials Lab | 0 | 0 | 4 | - | - | - | 20 | - | 30 | 50 | 2 |
| 8 | AMTME0253 | Seminar-I | | 0 | 0 | 2 | - | - | - | 50 | - | - | 50 | 1 |
| | | Total | | 15 | 0 | 10 | - | - | - | - | - | - | 650 | 20 |
| C | Departmental Ele | ective-III | AMTME0211 AMTME0212 AMTME0213 AMTME0214 | <u>2</u> 3 | | | Moo A | dern dvan | Manu Iiced V | ıfactu Veldir | ring T ng Teo | it Anal echno chnolo ynami | logy gy | |
| | | | AMTME021 | 5 | Advanced Mechanics of Solids | | | | | | | | | |
| | Departmental El | ective-IV | AMTME021 | 6 | Optimization Techniques | | | | | | | | | |
| - | | | AMTME021 | 7 | Artific | ial Inte | ellige | nce a | ind Ma | achine | Learr | ing(AI | ML) | |
| | | | AMTME021 | 8 | | | Ma | anage | emen | t Infor | matic | on Syst | tem | |
| | | | AMTME021 | 9 | | | F | lexib | le Ma | nufac | turing | l Syste | em | |
| | Departmental El | ective_V | AMTME022 | 0 | | | | | Mad | chine | Visior | า | | |
| | Departinental El | | AMTME022 | 1 | | | Ra | pid N | Manuf | actur | ing ar | nd Too | ling | |
| | | | AMTME0222 | | hhrev | | | | rid Ve | ehicle | Tech | nology | | |

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L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., PE: Practical End Semester Exam.

| | | M. TEC | H FIRST Y | (EAR | | | | |
|--|---|--|--|--------------------------------|-------------------------|---------------|---------|-----------------|
| Cours | e Code | AMTME0101 | | | L | Т | Р | Credit |
| Cours | e Title | Simulation, Modell | ing & Analys | sis | 3 | 0 | 0 | 3 |
| Integrati | 1 | Basic of Mechanical | Engineering, | Electrical | Engine | erin | lg, D | ifferentiation, |
| | | learn about the need of | f simulation a | nd differen | t statist | ical | mode | -1 |
| | | learn about Queue mo | | | i statist | icai | mou | -1. |
| | | learn about queue mo | | ion | | | | |
| | | learn about different fe | | | | | | |
| | | learn about Bond grap | | | | | | |
| - 1 | | • 1 | ontents / Sy | vllabus | | | | |
| UNIT- | I In | troduction | | y nuo us | | | | 09 hours |
| | | a tool, advantages and d | lisadvantages of | simulation. | areas of | app | licatio | |
| statistical distributio | models: queui ons: Bernoulli di | cepts in discrete event si ng systems; inventory sy stribution; Binomial distrib distribution, Exponential G | ystems; reliabili bution; Geometr | ty and main ic distributior | tainabili 1, continu | ty, l 10us | imited | data, discrete |
| UNIT- | II Qu | ueuing Models and | d Random | Numbers | s | | | 8hours |
| server ut Random generatin Random | ilization in G/C Number Gene ng random num Variate Gener | nism, queuing notations $G/1/\infty/\infty$ queues. eration: Properties of ra- abers, tests of random nu- ration: Inverse transfor- , Convolution Method, A | andom number umbers m technique, 1 | rs, Pseudo ra Direct trans | andom 1 formatio | num | bers, | techniques of |
| UNIT- | | put Modelling and | | | que | | | 09 hours |
| Input M identifica | odelling And ation, Paramet | Validation: Steps in the er estimation, Goodne ion of simulation models | he developmen ss of Fit Tes | nt of mode | | | | , Distribution |
| UNIT- | IV In | troduction to Sim | ulation soft | tware | | | | 08 hours |
| | | erent simulation softw | | | lation | sof | tware | |
| package | s, MATLAB, | Basic operation in M. | ATLAB. | | | | | |
| UNIT- | V A | pplication of MAT | LAB | | | | | 08 hours |
| Solving | | elated Mechanical | | Thermal, 1 | Kinema | ıtic | of | Mechanism, |
| Optimiz | ation etc. | | | | | | | |
| Textbo | ooks: | | | | | | | |
| 1. Simu | lation Modelli | ing and Analysis by La | aw and Keltor | n, Mc Graw | v Hill. | | | |
| 2. Simu | lation Model I | Design& execution by | Fishwich, Pr | entice Hall | | | | |
| 3. Discr | ete event syste | em simulation by Ban | ks, Carson, N | elson and N | Vicol. | | | |
| 2. MAT | LAB for Mec | hanical Engineers by | Rao V Dukki | i pati , Fairfi | eld Un | iver | sity | |
| Cours | e outcome: | · · · · · · · · · · · · · · · · · · · | | | | | | |
| Course | Modelling | Simulation and Anal | vsis | | | | | |
| 1 | | ll be able to analyse d | | tical model. | | | | K3 |
| 2 | | Il be able toanalyse a d | | | | lizat | tion | K3 |
| 3 | | Il be able to generate t | <u>^</u> | | | | | K2 |
| | | d on distribution. | | | | | | |
| 4 | Students wi | ll be able to verify and | l validate a m | odel. | | | | K4 |
| 5 | | | | | | | 1 | |
| 5 | ~~~~~ | vill be able to simu | late mechani | ical systen | n using | g S1 | mula | tion K4 |

| Course | e Code | AMTME0102 | L | Т | Р | Credit | | |
|---|--|---|---|--|--|---|-------------|--|
| Course | | Design of Experiments | 3 | 0 | 0 | 3 | - | |
| | quisites: Basi | ° 1 | | • | • | | - | |
| | e objective: | ics of statics | | | | | - | |
| Course | | ective is to learn how to plan, design and | conduct ex | neri | ment | s efficiently | - | |
| 1 | and effectively | | | | | | | |
| 2 | , , , , , , , , , , , , , , , , , , , | The objective is to analyze the resulting data to obtain objective conclusions. | | | | | | |
| 3 | The objective of the Taguchi's method is to produce high quality product at low cost to | | | | | | | |
| 3 | | the manufacturer | | | | | | |
| 4 | e e | The objective of Signal-to-noise ratio is a measure used in science and engineering that | | | | | | |
| т | compares the lev | vel of a desired signal to the level of backgr | round noise | э. | | | | |
| | | Course Contents / Syllabus | | | | | | |
| UNIT- | I Introdu | | | | | 09 hours | 1 | |
| | | , Typical applications of Experimental design | n, Basic Prin | ncip | es, G | uidelines for | | |
| | | ncepts of random variable, probability, density | | | | | | |
| | y, Concept of confi | lation, Measure of Central tendency; Mean dence level | median an | d m | ode, | Measures of | | |
| UNIT- | | mental design | | | | 8hours | - | |
| | - | inology: factors, levels, interactions, treatment | combination | ı, rai | ndom | | 1 | |
| | | | | | | | | |
| | | or two factors and three factors. Three-level ex | | | | | | |
| and three | factors, Factor eff | or two factors and three factors. Three-level ex fects, Factor interactions, Fractional factorial of | | | | | | |
| and three composite | factors, Factor eff e designs | ècts, Factor interactions, Fractional factorial o | | | | igns, Central | - | |
| and three composite | factors, Factor eff e designs III Analys | ects, Factor interactions, Fractional factorial c is and Interpretation Methods | design, Satu | rate | l Des | igns, Central 09 hours | - | |
| and three composite UNIT- Measures | factors, Factor eff e designs III Analys of variability, Rar | Tects, Factor interactions, Fractional factorial of is and Interpretation Methods hking method, Column effect method & Plott | design, Satu ting method | rateo | l Des | igns, Central 09 hours s of variance | - | |
| and three composite UNIT- Measures (ANOVA | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da | is and Interpretation Methods hking method, Column effect method & Plott eriments: YATE's algorithm for ANOVA, R tta | design, Satu ting method Regression a | rateo , Ar analy | l Des | igns, Central 09 hours of variance Mathematical | - | |
| and three composite UNIT- Measures (ANOVA models fro UNIT- | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da IV Experi | Sects, Factor interactions, Fractional factorial of is and Interpretation Methods hking method, Column effect method & Plott periments: YATE's algorithm for ANOVA, R atta ment Design Using Taguchi's Orthog | design, Satu ting method Regression a gonal Arr a | , Ar naly | l Des alysis | igns, Central 09 hours of variance Mathematical 08 hours | | |
| and three composite UNIT- Measures (ANOVA models fro UNIT- Types of C | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da IV Experi Orthogonal Arrays, | Sects, Factor interactions, Fractional factorial of is and Interpretation Methods hking method, Column effect method & Plott eriments: YATE's algorithm for ANOVA, R ata ment Design Using Taguchi's Orthog selection of standard orthogonal arrays, linear | design, Satu ting method Regression a gonal Arra graphs and | , Ar naly | l Des alysis | igns, Central 09 hours of variance Mathematical 08 hours | - | |
| and three composite UNIT- Measures (ANOVA models fro UNIT- Types of 0 Dummy le | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da IV Experi Orthogonal Arrays, evel Technique, Co | Factor interactions, Fractional factorial of is and Interpretation Methods Inking method, Column effect method & Plotteriments: YATE's algorithm for ANOVA, Restance Ment Design Using Taguchi's Orthog selection of standard orthogonal arrays, linear Impound factor method, Modification of linear set | design, Satu ting method Regression a gonal Arra graphs and | , Ar naly | l Des alysis | igns, Central 09 hours of variance Mathematical 08 hours n assignment, | | |
| and three composite UNIT- Measures (ANOVA models fro UNIT- Types of C Dummy la UNIT- | factors, Factor eff e designs Manalys of variability, Rar) in Factorial Exp om experimental da IV Experi Orthogonal Arrays, evel Technique, Co V Signal | Tects, Factor interactions, Fractional factorial of is and Interpretation Methods hking method, Column effect method & Plott eriments: YATE's algorithm for ANOVA, R ta ment Design Using Taguchi's Orthog selection of standard orthogonal arrays, linear mpound factor method, Modification of linear a to Noise Ratio | design, Satu ting method Regression a gonal Arra graphs and graphs | , Ar unaly ays Inter | l Des alysis vsis, 1 | igns, Central 09 hours s of variance Mathematical 08 hours assignment, 08 hours | | |
| and three composite UNIT- Measures (ANOVA models free UNIT- Types of C Dummy le UNIT- Evaluation | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da IV Experi Orthogonal Arrays, evel Technique, Co V Signal n of sensitivity to n | Tects, Factor interactions, Fractional factorial of is and Interpretation Methods aking method, Column effect method & Plott periments: YATE's algorithm for ANOVA, R ta ment Design Using Taguchi's Orthog selection of standard orthogonal arrays, linear mpound factor method, Modification of linear a to Noise Ratio oise. Signal to Noise ratios for static problems: | design, Satu ting method Regression a gonal Arra graphs and graphs : Smaller-the | rated , Ar analy ays Inter | alysis alysis, l action | igns, Central 09 hours s of variance Mathematical 08 hours n assignment, 08 hours pe, Nominal- | | |
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| and three composite UNIT- Measures (ANOVA models fro UNIT- Types of 0 Dummy le UNIT- Evaluation the -bette arrays, par Textbo D.C. Mon X. Madhav S Jersey 070 Reference Taghuchi 04124002 Philip J. Parameter | factors, Factor eff e designs III Analys of variability, Rar) in Factorial Exp om experimental da IV Experi Orthogonal Arrays, evel Technique, Co V Signal n of sensitivity to n er-type, Larger-the- rameter design strat Ocks: ntgomery, Design at S. Phadke, Quality 632,1989, ISBN: 01 e Books Robert H and Western Met 200 Ross, Taguchi Te r and Tolerance Desi | Tects, Factor interactions, Fractional factorial of is and Interpretation Methods aking method, Column effect method & Plott eriments: YATE's algorithm for ANOVA, R ta ment Design Using Taguchi's Orthog selection of standard orthogonal arrays, linear mpound factor method, Modification of linear y to Noise Ratio oise. Signal to Noise ratios for static problems: better type. Parameter and tolerance design co tegy, tolerance design strategy nd Analysis of Experiments, Wiley India, 5th F Engineering Using Robust Design, Prentice F 137451679 L Lochner, Joseph E. Matar, Designing for O thods or Statistical Experimental Design, Ch | design, Satu ting method Regression a gonal Arra graphs and graphs : Smaller-the oncepts, Tag Edition, 200 Hall PTR, E Quality - an hapman and unction, Ort 0070539588 | rated , Ar unaly ays Inter e-bec guch 6, IS ngle h Int | 1 Des alysis rsis, 1 action ter ty 's inn BN - wood roduc Il, 19 onal | igns, Central 09 hours s of variance Mathematical 08 hours n assignment, 08 hours pe, Nominal- her and outer - 812651048- Cliffs, New ction Best of 190, ISBN – | | |
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| | | M. TECH FIRST YEAR | | | | | |
|--------------|---|---|-------|-------|--------|---------|----------------------------------|
| Course | Code | AMTCC0101 | L | Т | Ρ | Crec | lit |
| Course | Title | Research Process & Methodology | 3 | 0 | 0 | 3 | |
| Course | object | ive: | | | | | |
| 1 | To unc | erstand the concept / fundamentals of research and the | ir ty | pes | | | |
| 2 | To und | erstand the methods of research design and steps of rese | earc | :h p | roces | S | |
| 3 | To understand the methods of data collection and procedure of sampling tech | | | | | | |
| 4 | | yse the data, apply the statistical techniques and unders | tan | d th | e con | cept o | f |
| 5 | | esis testing erstand the types of research report and technical writing | ~ | | | | |
| | | : Basics of Statistics | g. | | | | |
| | | Course Contents / Syllabus | | | | | |
| UNIT | -T | Introduction to Research | | | | 8 | hours |
| | | tive and motivation of research, Types and approaches | of r | esea | arch. | Descri | ntive vs. |
| | | lied vs. Fundamental, Quantitative vs. Qualitative, | | | | | |
| • | | ls versus Methodology, significance of research, criteria c | | | | | I , |
| UNIT | | Research Formulation and Design | | | | | hours |
| | | s and steps involved, Definition and necessity of researc | h pi | robl | em. I | mport | ance and |
| | | rature review, locating relevant literature, Reliability of | | | | | |
| | | the research problem, Literature Survey, Research De | | | | • | • |
| design. | | | U | | | | |
| UNIT | -III | Data Collection | | | | 8 | hours |
| Classific | ation of | Data, accepts of method validation, Methods of Data | ı C | olle | ction, | Colle | ection of |
| primary | and sec | ondary data, sampling, need of sampling, sampling theor | y a | nd ' | Techr | niques, | steps in |
| sampling | g design, | different types of sample designs, ethical considerations | in r | esea | arch. | - | - |
| UNIT | -IV | Data Analysis | | | | 8 | hours |
| Processi | ng Oper | ations, Data analysis, Types of analysis, Statistical te | chn | ique | es an | d cho | osing an |
| appropria | ate stati | stical technique, Hypothesis Testing, Data processing | sof | twa | re (e. | g. SP | SS etc.), |
| statistica | 1 infere | nce, Chi-Square Test, Analysis of variance (ANOV | A) | and | d co | variano | ce, Data |
| Visualiza | ation – N | Aonitoring Research Experiments, hands-on with LaTeX. | | | | | |
| UNIT | -V | Technical writing and Reporting of Research | | | | 8 | hours |
| Types of | of resea | urch report: Dissertation and Thesis, research pap | | rev | view | articl | e. short |
| | | conference presentation etc., Referencing and referencing | | | | | |
| Indexing | | ation of Journals and Impact factor, | | ypes | | | Indexing- |
| <u> </u> | ., | COPUS/DBLP/Google Scholar/UGC-CARE etc. Significand | • | | | | \mathcal{O} |
| | | m, IPR- intellectual property rights and patent law, con | | | | | |
| | | ated aspects of intellectual property rights (TRIPS); sch | | | | | |
| | | gn of research paper, reproducibility and accountability. | |) | | 8 | |
| <u>^</u> | | me: Upon completion of the course, the student will b | e al | ole (| to: | | |
| CO 1 | | he concept / fundamentals for different types of research | | | | | K ₂ |
| CO 1 CO 2 | | relevant research Design technique | | | | | K ₂ K ₃ |
| | | | | | | | |
| CO 3 | | propriate Data Collection technique | | | | | K ₃ |
| CO 4 | | e statistical analysis which includes various parametr tric test and ANOVA technique | ic | test | and | non- | K5 |
| | Parame | | | | | | L |

| CO 5 Prepare research report and Publish ethically. | K ₆ |
|---|--------------------------|
| Text books | |
| 1. C. R. Kothari, Gaurav Garg, Research Methodology Methods and Technique | es, New Age |
| International publishers, Third Edition. | |
| 2. Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, | 2 nd Edition, |
| SAGE 2005. | |
| 3. Deepak Chawla, NeenaSondhi, Research Methodology, Vikas Publication | |
| Reference Books | |
| 1.Donald Cooper & Pamela Schindler, Business Research Methods, TMGH, 9th edition | on |
| 2.Creswell, John W, Research design: Qualitative, quantitative, and mixed methods a | pproach |
| sage publications, 2013 | |

| | | | M. TECH FIRST YEAR | | |
|----|------------|------------|--|------------|----------|
| Co | ourse | e Code | AMTME0151 | LTP | Credits |
| Co | ours | e Title | Simulation, Modelling & Analysis Lab | 004 | 2 |
| Co | urse | e objecti | ives: | | |
| 1 | FLU | UENT, et | e fundamental knowledge on using various analytical to c., for Engineering Simulation. | | |
| 2 | imp | prove the | rious fields of engineering where these tools can be ef output of a product. | - | |
| 3 | | | nowledge on how these tools are used in Industries by s as using these tools. | olving so | ome real |
| | | quisites | | | |
| _ | No | s snould n | ave basic knowledge of Engineering. LIST OF EXPERIMENTS (Total Eight to be perform | med) | |
| 1 | 1 | Study of | simulation software Like ARENA, MATLAB. | | |
| 2 | 2 | Simulati | on of translational and rotational mechanical systems | | |
| 3 | 3 | Simulati | on of Queuing systems | | |
| 4 | 1 | Simulati | on of Manufacturing System | | |
| 5 | 5 | Generati | ion of Random number | | |
| (| 5 | Modelli | ng and Analysis of Dynamic Systems | | |
| 7 | 7 | | on mass spring damper system | | |
| 8 | 8 | | on of hydraulic and pneumatic systems. | | |
| 9 |) | | on of Job shop with material handling and Flexible manufa | acturing s | systems |
| 1 | 0 | Simulati | on of Service Operations | | |
| Co | urse | e outcon | I | | |
| CC | 01 | | lent will be able to appreciate the utility of the tools like A T in solving real time problems and day to day problems. | ANSYS o | r K2 |
| CC | D 2 | | hese tools for any engineering and real time applications. | | K2 |
| CC |) 3 | curricul | knowledge on utilizing these tools for a better projectum as well as they will be prepared to handle industry afidence when it matters to use these tools in their employr | problem | |

| | | M. TECH FIRST YEAR | |
|-------------|-----------------------|--|----------------------|
| | se Code | AMTME0152 L T P | Credit |
| Cours | se Title | Industry 4.0 LAB 0 0 4 | 2 |
| Cours | se objective | es: | |
| 1 | Students v | will be able to understand and implement the concepts of Industry | 4.0 |
| 2 | | students understand and implement the concepts of Industrial IOT | |
| 3 | | arize students with concepts of Robotics, AI/ML and AR/VR Tech | |
| 4 | | udents understand and implement the concepts Additive Manu | facturing and |
| | Reverse Eng | ineering. | |
| | equisites: | | |
| | ts should hav | e basic knowledge of Engineering. | |
| S. No | LIST OF E | EXPERIMENTS (Total Eight to be performed) | |
| | | | |
| 1 | | Smart Factory setup based on Industry 4.0 | |
| 2 | | ensing and Actuating systems used in Industrial IOT | |
| 3 | Familiarizat | tion with concept of IoT, Arduino/Raspberry Pi and perform nece | ssary |
| 3 | software ins | stallation | |
| 4 | Develop an | IoT based smart lock system for Motor cycle/Car | |
| 5 | Creating a r | model using Augmented Reality (AR/VR Technology) | |
| | | atural Language Processing including Syntactic, Semantic, Discou | urse and |
| 6 | Pragmatic F | | |
| | <u> </u> | earning Project using Python for Linear Regression analysis of fue | |
| 7 | consumptio | | |
| 8 | - | Robot to perform Pick and place operation using a structured pro | arom |
| ð | | | - |
| 9 | - | Simulate the task of Pick the pencil from the magazine and draw | rectangle & |
| | Square | | |
| 10 | | nt of a designed model with given parameters on FDM RP System | |
| 11 | - | nt of a designed model with given parameters on SLA RP System | |
| 12 | | point cloud data(3D model) of mechanical components using 3D | Scanning |
| 12 | Technology | 7 | |
| ~ | | | |
| | <u>se outcome</u> | 1 1 | |
| CO 2 | | e familiar with the concept of Industry 4.0 | K ₂ |
| CO 2 | | and and implement fundamentals of Industrial IOT | K ₂ |
| CO S | B Practica Technol | illy implement the concepts of Robotics, AI/ML and AR logy. | /VR K ₂ |
| CO 4 | 4 Learn a Enginee | and implement the concepts Additive Manufacturing and Revering. | verse K ₂ |

| | | M. TECH FIRST YEAR | | |
|--------|---------------------------|---|--------------|----------------|
| Cou | rse Code | AMTME0111 | LTP | Credit |
| Cou | rse Title | Geometric Design & Rapid Prototyping | 3 0 0 | 3 |
| Соц | rse objective: | | | |
| 1 | | edge on various Geometric Design & Rapid Proto Typi | ng so that | the students |
| 1 | * | n engineering industry applications. | ing so that | the students |
| 2 | | nding of modelling and design based on component geo | metry | |
| 3 | v | nowledge on the design of various components. | Jineti y | |
| 4 | | ledge and to solve problems associated with design and | ranid prot | otyping and |
| · | ▲ | ts on the latest technology to ensure computer aided main | A A | •••• |
| | | a good operating condition and at low maintenance cost | | s una aosign |
| 5 | | edge on prototyping systems as well as learn how to per | | c procedures |
| | on a system. | | | procedures |
| Pre_ | -requisites: | | | |
| 110- | requisites. | Course Contents / Syllabus | | |
| TINIT | | v | | 4.1 |
| UNI | | Geometric Design- Introduction: | | 4 hours |
| | 1 | of CAD/CAM, Introduction to design process and ro | ole of com | puters in the |
| • | n process. | | | |
| | | Analytical, Synthetic curves with advantages, Disadvan | • | * |
| | | cometric modelling curves and surfaces, Representation | | |
| | - | tions, Parametric curves and surfaces, Manipulations | of curves | and surfaces, |
| | | fid point line, circle, ellipse algorithms. | | |
| | T-II | Solid modelling: | | 12hours |
| | | entals of solid modelling, Different solid representation | | |
| Boun | idary representat | ion (B-rep), Constructive solid geometry (CSG), | Sweep re | epresentation, |
| | | ng, Perspective, Parallel projection, Hidden line remova | al algorithr | |
| | T-III | Rapid Prototyping-Introduction: | | 8hours |
| | | yping, Traditional Prototyping Vs. Rapid Prototyping | | ssification of |
| - | | Processes: Additive, Subtractive, Formative, Generic R | P process. | |
| | T-IV | Rapid Prototyping Process | | 8 hours |
| Proce | ess Physics, Too | oling, Process Analysis, Material and technological | aspects, | Applications, |
| limita | ations and com | parison of various rapid manufacturing processes | s. Photop | olymerization |
| · | • • • • | L), Microstereolithography, Powder Bed Fusion (Se | | • |
| | | melting (EBM)), Extrusion-Based RP Systems (Fused | | |
| · | ,,, · | , Sheet Lamination (Laminated Object Manufacturi | • | |
| | | Beam Deposition (Laser Engineered Net Shaping | (LENS), | Direct Metal |
| | osition (DMD) | | | |
| | T-V | CAD/CAM | | 8 hours |
| | A A | on, Data interfacing: formats (STL, SLC, CLI, RPI, LE | | |
| | | validity checks, repair procedures; Part orientation a | * * | • |
| | | sign, Model Slicing algorithms and contour data o | rganization | n, direct and |
| adapt | tive slicing, Tool | path generation. | | |
| p | | After completion of this course students will be a | ble to | |
| | rse outcome: | Arter completion of this course students will be a | | |
| | 1 Explain the | concepts and underlying theory of modelling and the u lifferent engineering applications. | | K1,K2 |
| Cou | 1 Explain the models in c | e concepts and underlying theory of modelling and the u | sage of | |

| CO 3 | Understand and use techniques for processing of CAD models for rapid | |
|------|--|---------|
| | prototyping. | |
| CO 4 | Understand and use techniques for processing of CAD Understand and apply | K3, K4, |
| | fundamentals of rapid prototyping techniques. | K5 |
| CO 5 | Use current state-of-the-art CAD/CAM technology in research. | K3,K4 |
| | | |

Text Books& Reference Books:

1. Chua C K, Leong K F, Chu S L, Rapid Prototyping: Principles and Applications in Manufacturing, World Scientific.

2. Gibson D W Rosen, Brent Stucker., Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing, Springer.

3. Noorani R, Rapid Prototyping: Principles and Applications in Manufacturing, John Wiley & Sons.

4. Computer Aided Engineering & Design Jim Browne New ATC International

5. The Engineering Database D.N. Chorafas and S.J. Legg Butterworths

6. Principles of CAD J Rooney &P Steadman Longman Higher Education

7. CAD/CAM H P Groover and E W Zimmers Prentice Hall

8. Computer Integrated Design and Manufacture D Bedworth, M Henderson & P Wolfe MacGraw Hill Inc.

| | M.TECH FIRST YEAR | | |
|---|---|--|---|
| de AMTME0 | 112 | L T P | Credit |
| | d Heat and Mass Transfer | 3 0 0 | 3 |
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| | undamental concepts of conduction and | l its application | 8 |
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| o understand and | demonstrate the principles of radiation a | and heat transfe | r phenomenon |
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| | pasic concepts of mass transfer and its ap | pplications | |
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| circular tubes. | - | lartineli's analo | ogies, Turbulent |
| circular tubes. Mass Ti | ransfer | | ogies, Turbulent 8 hours |
| circular tubes. Mass Tr er: Definition, Ex | amples, Fick's law of diffusion, Fick's | a law as referre | 8 hours d to ideal gases, |
| circular tubes. Mass Tr er: Definition, Ex Isothermal Equi- | ransfer amples, Fick's law of diffusion, Fick's molal counter diffusion of ideal gases | a law as referre s, Mass diffusi | 8 hours d to ideal gases, vity, Gilliland's |
| circular tubes. Mass Tu er: Definition, Ex Isothermal Equi- thermal evaporat | ransfer amples, Fick's law of diffusion, Fick's molal counter diffusion of ideal gases ion of water and its subsequent diffus | a law as referre s, Mass diffusi | 8 hours d to ideal gases, vity, Gilliland's |
| circular tubes. Mass Tr er: Definition, Ex Isothermal Equi- | ransfer amples, Fick's law of diffusion, Fick's molal counter diffusion of ideal gases ion of water and its subsequent diffus | a law as referre s, Mass diffusi | 8 hours d to ideal gases, vity, Gilliland's |
| circular tubes. Mass Tr er: Definition, Ex Isothermal Equi- thermal evaporat Jumerical problem | ransfer amples, Fick's law of diffusion, Fick's molal counter diffusion of ideal gases ion of water and its subsequent diffus ns. | a law as referre s, Mass diffusi ion into dry ai | 8 hours d to ideal gases, vity, Gilliland's |
| circular tubes. Mass Tu er: Definition, Ex Isothermal Equi- thermal evaporat Jumerical problem | ransfer amples, Fick's law of diffusion, Fick's molal counter diffusion of ideal gases ion of water and its subsequent diffus | a law as referre s, Mass diffusi ion into dry ai vill be able to | 8 hours d to ideal gases, vity, Gilliland's r, Mass transfer |
| | Image: stand stan | Ite Advanced Heat and Mass Transfer jective: • o understand the fundamental concepts of conduction and o understand and demonstrate the principles of radiation arough radiation o study and identify the phenomenon in convection heat to o understand the basic concepts of mass transfer and its a sites: dge of Engineering Mechanics dge of Engineering Mechanics isite laws of Conduction, Convection and Radiation Conse Contents / Syllabus Q Conduction ional steady state conduction, with variable thermal of eat source, Local heat source in non-adiabatic plate, Therm Extended Surfaces urfaces-Review, Optimum fin of rectangular profile, so ofiles, Optimum profile, Circumferential fin of rectans. 2D steady state conduction, semi-infinite and finite nders and in infinite semi-cylinders, spherical shells, nsteady state conduction, Sudden changes in the surface d spheres using Groeber's and Heisler charts for plates, fluids. Radiation adiation principles, Diffuse surfaces, and the Lambert's ng media, Hottel's method of successive reflections, Geb diation through absorbing media, Logarithmic decreated f simple shaped gas bodies, Net heat exchange between station of luminous gas flames. Convection Heat transfer in laminar flow, free convection between circular tubes, fully developed flow, Velocity and therm l temperature and with constant heat flux, Forced extern velocity and temperature boundary layer equations, Ka | Ite Advanced Heat and Mass Transfer 3 0 0 jective: o understand the fundamental concepts of conduction and its applications of fins and study the design of fins o understand the applications of fins and study the design of fins o o understand and demonstrate the principles of radiation and heat transfer o understand the basic concepts of mass transfer and its applications o understand the basic concepts of mass transfer and its applications ittes: oge of Engineering Mechanics dge of Engineering Mathematics sisic laws of Conduction, Convection and Radiation Contrace Contents / Syllabus Conduction ional steady state conduction with variable thermal conductivity an eat source, Local heat source in non-adiabatic plate, Thermocouple conductions, Optimum fin of rectangular profile, straight fins of offiles, Optimum profile, Circumferential fin of rectangular profile, straight fins of offiles, Optimum profile, Circumferential fin of rectangular profile, straight state conduction, Sudden changes in the surface temperatures of a spheres using Groeber's and Heisler charts for plates, cylinders and s fluids. Radiation Image and the surfaces, and the Lambert's cosine law. Rage media, Hottel's method of successive reflections, Gebhart's unified r diation through absorbing media, Logarithmic decrement of radia f simple shaped gas bodies, Net heat exchange between surfaces separat diation of luminous gas flames. Convection |

| CO 2 Apply principles of heat transfer to develop mathematical models for uniform K ₃ , K | ŀ |
|---|---|
| and non-uniform fins | |
| Employ mathematical functions and heat conduction charts in tackling two K ₄ , K | ; |
| CO 3 dimensional and three-dimensional heat conduction problems. | |
| CO 4 Analyze free and forced convection problems involving complex geometries K ₃ , K ₄ | |
| with properboundary conditions. | |
| $CO 5$ Apply the concepts of radiation heat transfer for enclosure analysis. K_4 | |
| | |
| CO 6 Understand physical and mathematical aspects of mass transfer. K ₁ , K | 2 |
| Text Books | |
| (1) Principals of Heat Transfer/Frank Kreith/Cengage Learning | |
| (2)Elements of Heat Transfer/E. Radha Krishna/CRC Press/2012 | |
| (3)Heat Transfer/RK Rajput/S.Chand | |
| ReferenceBooks | |
| (1) Introduction to Heat Transfer/SK Som/PHI | |
| (2) Engineering Heat & Mass Transfer/Mahesh Rathore/Lakshmi Publications | |
| | |
| (3)Heat Transfer / NecatiOzisik / TMH | |
| | |

| | | M. TECH FIRST YEAR | | | | |
|---|---|---|--|---|--|--|
| Course (| Code | AMTME0113 L 7 | ГР | Credit | | |
| Course 7 | ſitle | Renewable Energy System3 |) () | 3 | | |
| Course o | bjectiv | /e: | | | | |
| | | idents understand the concept of renewable and non- renew | able er | nergy | | |
| | ources. | | | | | |
| | | | | | | |
| | utilization. | | | | | |
| | To make students understand biogas generation, and hydro-electric generation and its impact on environment. | | | | | |
| | | idents able to identify wind energy as an alternate source of | anara | v and to | | |
| | | how it can be trapped. | energ | y and to | | |
| | | idents aware of the Concept of integration of conventional a | and not | n- | | |
| | | l energy resources and systems. | ina no | u | | |
| Pre-requ | | | | | | |
| | | thermal Engineering. | | | | |
| | | Course Contents / Syllabus | | | | |
| UNIT-I | Ι | ntroduction | | 8 hours | | |
| | ion: En | ergy and Development; Energy demand and availabili | | | | |
| | | Nonconventional energy; Renewable and Non-renewable | | | | |
| | | pacts of conventional energy usage; Basic concepts of h | . | | | |
| useful for e | | | | | | |
| UNIT-II | | olar Energy Systems | 81 | hours | | |
| LICCIO CI | hemical | tems: Solar radiations data; Solar energy collection, Stora | | | | |
| | olar stora on and A | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems | affec | ting energy generation; | | |
| Refrigerati | olar stora on and A | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems | affec Power | ting energy generation; 8 hours | | |
| Refrigerati UNIT III Micro and power; Mid | olar stora on and A [N d Small cro, min | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec | affec Power | ting energy generation; 8 hours small hydro | | |
| Refrigerati UNIT III Micro and power; Mic heads; Velo | olar stora on and A [N d Small cro, min ocity he | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Speciad turbines; Hydrams; Water-mill; Tidal power. | affec Power | ting energy generation; 8 hours small hydro ines for low | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV | olar stora on and A I N d Small cro, min ocity hea 7 I | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems | affec Power | ting energy generation; 8 hours small hydro ines for low 8 hours | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass | olar stora on and A I N d Small cro, min ocity hea A Energy | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spect ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, m | affec Power and sial eng | ting energy generation; 8 hours small hydro ines for low 8 hours al and other | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass residues; (| olar stora on and A I N d Small cro, min ocity hea A Energy Optimiza | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems | affec Power and sial eng | ting energy generation; 8 hours small hydro ines for low 8 hours al and other | | |
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| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass I residues; C fuels; Biog UNIT V | olar stora on and A Market Small cro, min ocity hea A Continue Continue State Continue Continto Continto Continue Continue Continue Continue Continue Contin | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Speciad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, mation of bio-mass utilization, Bio mass conversion technoloucer gas; Power alcohol from biomass; Power generation. | affec Power and s al eng unicip nologie | ting energy generation 8 hours small hydro ines for low 8 hours al and other es; Cooking hours | | |
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| Refrigerati UNIT III Micro and power; Micheads; Velo UNIT-IV Bio-mass I residues; C fuels; Biog UNIT V Wind End Economics | olar stora on and A d Small cro, min ocity hea A Energy Optimiza gas; prod V ergy Sy s of wind | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, m ation of bio-mass utilization, Bio mass conversion techn lucer gas; Power alcohol from biomass; Power generation. Wind Energy Systems Stems: Wind data; Horizontal and vertical axis windm | affec Power and state and all eng nologie 8 1 iills; V | ting energy generation; 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass I residues; C fuels; Biog UNIT V Wind End Economics Integrated | olar stora on and A M Small cro, min ocity hea A Detimiza gas; prod Softwing sof wing I Energy | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, m ation of bio-mass utilization, Bio mass conversion techn lucer gas; Power alcohol from biomass; Power generation. Vind Energy Systems Stems: Wind data; Horizontal and vertical axis windm d energy. | affec Power and s al eng unicip nologie 8 l iills; V non-c | ting energy generation; 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass I residues; (C fuels; Biog UNIT V Wind End Economics Integrated energy reso | olar stora on and A Market Small cro, min ocity hea A Small cro, min ocity hea A Small cro, min ocity hea A Small A Small C Small C Small C Small C Small C Small C Small C Small C Sm | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, mation of bio-mass utilization, Bio mass conversion technolucer gas; Power alcohol from biomass; Power generation. Vind Energy Systems Stems: Wind data; Horizontal and vertical axis windmal energy. Systems: Concept of integration of conventional and nd systems; Integrated energy system design and economic | affec Power and state and all eng unicip nologie 8 l iills; V non-c s. | ting energy generation; 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms; conventional | | |
| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass I residues; C fuels; Biog UNIT V Wind End Economics Integrated energy reso | olar stora on and A Market Small cro, min ocity hea A min ocity hea A min ocity hea A min Senergy Optimiza gas; prod A min Senergy Sys of wince a sof wince a min Sources a Dutcom | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spectad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, mation of bio-mass utilization, Bio mass conversion technolucer gas; Power alcohol from biomass; Power generation. Wind Energy Systems Stems: Wind data; Horizontal and vertical axis windmatherergy. Systems: Concept of integration of conventional and nd systems; Integrated energy system design and economic e: After completion of this course students will be a | affec Power and s al eng unicip nologie 8 l ills; V non-c s. | ting energy generation 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms | | |
| Refrigerati UNIT III Micro and power; Midhads; Velocity beads; Velocity UNIT-IV Bio-mass residues; Control fuels; Biog UNIT V Wind End Economics Integrated energy reso Course o CO 1 | olar stora on and A Market Small cro, min ocity hea ocity hea A Energy Optimiza gas; prod V ergy Sy s of wince I Energ ources an Ources an Perceive | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Speciad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, mation of bio-mass utilization, Bio mass conversion technucer gas; Power alcohol from biomass; Power generation. Wind Energy Systems Stems: Wind data; Horizontal and vertical axis windmatherergy. Systems: Concept of integration of conventional and nd systems; Integrated energy system design and economic e: After completion of this course students will be a the concept of renewable and non-renewable energy | affec Power and s al eng unicip nologie 8 l ills; V non-c s. | ting energy generation, 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms | | |
| Refrigerati UNIT III Micro and power; Midhads; Velocity beads; Velocity UNIT-IV Bio-mass residues; C fuels; Biog UNIT V Wind End Economics Integrated energy reso Course o CO 1 P res | olar stora on and A Market Small cro, min ocity hea A Small cro, min ocity hea A Small Energy Dytimiza gas; prod Vergy Sy s of wince I Energy ources an Ources an Perceive esources | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Speciad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, mation of bio-mass utilization, Bio mass conversion technucer gas; Power alcohol from biomass; Power generation. Wind Energy Systems Stems: Wind data; Horizontal and vertical axis windmatherergy. Systems: Concept of integration of conventional and nd systems; Integrated energy system design and economic e: After completion of this course students will be a the concept of renewable and non-renewable energy and systems. | affec Power and states and states and eng unicip nologie 8 l iills; V non-c s. ble to y K2 | ting energy generation 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms conventional | | |
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| Refrigerati UNIT III Micro and power; Mid heads; Veld UNIT-IV Bio-mass I residues; C fuels; Biog UNIT V Wind End Economics Integrated energy reso CO 1 P re CO 2 R a CO 3 A | olar stora on and A M Small cro, min ocity hea Z Energy Optimiza gas; prod V ergy Sy s of wince I Energ ources at ources at Perceive esources Recogniz long-wit Apply th | Storage, (Li-ion, Li-Po, Lead Acid, salt water) factors age options, Solar water heating; Solar air heating; Solar Air-conditioning. Micro and Small Hydro Energy Systems Hydro Energy Systems: Resource assessment of micro i and small hydro power systems; Pump and turbine; Spec ad turbines; Hydrams; Water-mill; Tidal power. Bio-mass Energy Systems Systems: Availability of bio mass, agro, forest, animal, m ation of bio-mass utilization, Bio mass conversion techn ucer gas; Power alcohol from biomass; Power generation. Wind Energy Systems&Integrated Energy Systems stems: Wind data; Horizontal and vertical axis windm d energy. y Systems: Concept of integration of conventional and nd systems; Integrated energy system design and economic e: After completion of this course students will be a the concept of renewable and non-renewable energy at a solar energy collection and conversion | affec Power and sial eng unicip nologie 8 l iills; V non-c s. ble to y K2 n K ₃ , | ting energy generation; 8 hours small hydro ines for low 8 hours al and other es; Cooking hours Vind farms; conventional | | |

| CO 4 | Categorize various windmills and their utilization based on their characterization. | K ₃ , K ₄ |
|-------|---|---------------------------------|
| CO 5 | Integrate conventional and non-conventional energy resources and systems for betterment of society. | K ₄ |
| | | |
| Text | Books | |
| 1. | Energy Efficient Buildings in India Mili Majumdar Tata Energy Research | h Institute |
| 2. | Renewable Energy Systems Simmoes Marcelo Godoy CRC Press | |
| 3. | Renewable Energy Resources John Twidell Taylor and Francis | |
| Refer | enceBooks | |
| 1. | Renewable Energy Sources and Their Environmental Impact Abbasi & A | Abbasi PHI |
| 2. | Solar Energy - Principles of Thermal Collection and Storage by S P Suk | hatme |
| 3. | Solar Engineering of Thermal Processes by J ADuffie and W A Beckman | 1 |
| 4. | Principles of Solar Engineering by D Y Goswami and J F Kreider | |
| 5. | Introduction to Sustainable Engineering by R L Rag and Leks | |

| | | M. TECH FIRST YEAR | | | | |
|---|---|---|---|---------------------------------------|--|--|
| Co | urse Code | AMTME0114 | LTP | Credit | | |
| Co | urse Title | Reliability, Maintenance Management & Safety | 300 | 3 | | |
| Co | urse object | ive: | I | | | |
| 1 | | idents able to understand the concept of reliability, its | componen | ts and | | |
| | | used to enhance it. | I | | | |
| 2 | To make stu | idents perceive the knowledge of maintainability, available | lability, an | d failure, | | |
| along with its effect on quality. | | | | | | |
| 3 | 3 To get students able to integrate the concept of maintenance planning and replacement | | | | | |
| | | he concept of inspection. | | | | |
| 4 | | idents able to use various monitoring techniques, and | its impact o | on | | |
| _ | reliability. | | 1 . | 1. 1 . | | |
| 5 | | idents make aware of various safety aspects and hazar | ds associat | ed in plant | | |
| | e-requisites | f Industrial engineering | | | | |
| | | Course Contents / Syllabus | | | | |
| UN | IT-I | Reliability Engineering | | 8 hours | | |
| Mai Intro off Typ | intainability, oduction, form among reliab bes of failure | Maintainability, Availability & Failure Analysis Availability & Failure Analysis: Maintainabilit nulae, Techniques available to improve maintainabilit ility, maintainability & availability, simple problems es, defects reporting and recording, Defect analys | ty & Ava y & availal , Defect go sis, Failur | oility, trade eneration – | | |
| Equ | | time analysis, Breakdown analysis, TA, FMEA, FME | CA. | | | |
| | | Maintenance Planning and Replacement | | 8 hours | | |
| Mea equi prev Mai failu Insp | aning and c ipment subje ventive repla intenance syst ure, Opportun pection decisi | anning and Replacement: Maintenance planning – lifference, Optimal overhaul/Repair/Replace main | ntenance j nal interva | policy for al betweer placement | | |
| | vi ili iliailiteila | ct to breakdown, Replacement decisions – Optim cements of equipment subject to breakdown, tems, Fixed time maintenance, Condition based ma ity maintenance, design out maintenance, Total pro on – Optimal inspection frequency, non-destructive nce, Concept of terro technology. | ductive m | aintenance | | |
| UN | IT-IV | cements of equipment subject to breakdown, tems, Fixed time maintenance, Condition based ma ity maintenance, design out maintenance, Total pro on – Optimal inspection frequency, non-destructive | ductive mainspection | aintenance , PERT & 8 hours | | |

| diagnosis. | | |
|-------------------|---|---------------------------------|
| UNIT V | Safety Aspects | 8 hours |
| Safety Aspects: | Importance of safety, Factors affecting safety, Safety aspec | ts of site and |
| plant, Hazards | of commercial chemical reaction and operation, Instrume | ents for safe |
| operation, Safety | y education and training, Personnel safety, Disaster planning a | nd measuring |
| safety effectiven | ess, Future trends in industrial safety. | |
| Course outco | me: After completion of this course students will be ab | le to |
| CO 1 | Perceive the concept of reliability, its components and techniques used in it. | K2, K3 |
| CO 2 | Incorporate maintainability, availability, and failure in quality. | K ₃ , K ₄ |
| CO 3 | Integrate maintenance planning, replacement, and inspection to quality. | K4, K5 |
| CO 4 | Make use of various monitoring techniques used. | K ₃ , K ₄ |
| CO 5 | Get knowledge on various safety aspects and hazards associated in various industries. | K4 |
| | | |
| Text Books | eliability Engineering L.S. Srinath Affiliated East West Press | |
| 2.Maintainabilit | y and Reliability Handbook Editors: Ireson W.A. and C.F. Coo | mbs McGraw |
| Hill Inc. | | |
| 3.Failure Diagno | osis and Performance Monitoring L.F. Pau Marcel Dekker | |
| ReferenceBo | | |
| | ntenance Management S.K. Srivastava S. Chand & Co Ltd. | |
| | of Industrial Maintenance Kelly and M.J. Harris Butterworth an | d Co. |
| | Replacement and Reliability A.K.S. Jardine Pitman Publishing | |
| | Anitainability: How to Design for Reliability and Easy Main | ntenance B.S |
| Dhillon Prentice | | |
| 5.maustriai Mai | ntenance Management S.K. Srivastava S. Chand & Co Ltd. | |

| l | | M. TECH FIRSTYEAR | | |
|---|---|---|----------------------------------|--|
| Course Coo | le | AMTME0115 L T | P | Credit |
| Course Tit | | Turbo Machines 3 0 0 |) | 3 |
| Course obj | | | - | |
| 1 | | y the basics of turbomachinery | | |
| 2 | | y the energy transfer in nozzles and the design of steam turk | oine bl | ades |
| 3 | | y the fundamentals and design of centrifugal compressors | | |
| 4 | | y the fundamentals and design of axial flow compressors | | |
| 5 | | y and analyse the design of axial flow gas turbine | | |
| Pre-requisi | | , | | |
| | | ineering Mechanics | | |
| | | ineering Mathematics | | |
| | | f thermodynamics | | |
| Reviews of bas | ic laws of | f fluid mechanics | | |
| | | Course Contents / Syllabus | | |
| UNIT-I | Fur | idamentals of Turbo Machines | | 8 hours |
| Classification | s, Appl | ications, Thermodynamic analysis, Isentropic flow. | Energ | |
| Efficiencies, S | Static an | d Stagnation conditions, Continuity equations, Euler's flow | v throu | gh variable |
| cross-sectiona | l areas, l | Unsteady flow in turbo machines | | |
| UNIT II | Stea | am Nozzles | | 8 hours |
| Convergent a | and Cor | vergent-Divergent nozzles, Energy Balance, Effect of | back | pressure of |
| analysis. Desi | igns of 1 | nozzles. Steam Turbines: Impulse turbines, Compounding | , Wor | k done and |
| Velocity trian | gle, Effi | ciencies, Constant reactions, Blading, Design of blade part | ssages, | Angle and |
| height, Secon | dary flov | v. Leakage losses, Thermodynamic analysis of steam turbin | es | |
| UNIT-III | Gas | b Dynamics | | 8 hours |
| Fundamental | thermod | ynamic concepts, isentropic conditions, mach numbers a | nd are | a, Velocity |
| | | essure, Normal shock relation for perfect gas. Supersonic fl | | |
| | | k recoveries, Detached shocks, Aerofoil theory. Centrif | | |
| • • | • • | gles and efficiencies, Blade passage design, Diffuser and j | | • |
| | | l Stodolas formula's, Effect of inlet mach-numbers, Pre whi | | |
| UNIT IV | Axia | ll Flow Compressors | 8 | hours |
| Flow Analysis | s, Work | and velocity triangles, Efficiencies, Thermodynamic analys | sis. Sta | ge pressure |
| rise, Degree o | f reactio | n, Stage Loading, General design, Effect of velocity, Incide | ence, P | erformance |
| Cascade Anal | | | | |
| Cascaue Anal | ysis: Ge | ometrical and terminology. Blade force, Efficiencies, Losse | es, Fre | e end force, |
| Vortex Blades | 5. | | es, Fre | e end force, |
| | 5. | ometrical and terminology. Blade force, Efficiencies, Losse I Flow Gas Turbines | | e end force, hours |
| Vortex Blades UNIT V | S. Axia | | 8 | hours |
| Vortex Blades UNIT V Work done. V | 5. Axia Velocity | al Flow Gas Turbines | 8 Degree | hours of reaction, |
| Vortex Blades UNIT V Work done. V Zweifels relat | Axia Axia Velocity ion, Des | I Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D | 8 Degree | hours |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor | Axia Axia Velocity ion, Des tex blad | al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Corre | egree lations | of reaction, Secondary |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor Actuator disc | Axia Velocity ion, Des tex blad c, Theor | I Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Corre- e, Blade angles for variable degree of reaction. | egree lations | of reaction, Secondary |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor Actuator disc | Axia Velocity ion, Des tex blad c, Theor | I Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Correc e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and c | egree lations | of reaction, Secondary |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor Actuator disc Performances | Axia Velocity ion, Des rtex blad c, Theor , Matchi | I Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Corre- e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and c ng of compressors and turbines, Off design performance. | 8 Degree lations | of reaction, Secondary |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free von Actuator disc Performances | S. Velocity ion, Des tex blad c, Theor , Matchi | Al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Correl e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and c ng of compressors and turbines, Off design performance. After completion of this course students will be able | 8 Degree lations ooling | of reaction, Secondary of blades, |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor Actuator disc Performances Course out CO 1 H t | Axia Velocity ion, Des tex blad t, Theor , Matchi Come: Explain t ypes of 1 | I Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Correct e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and c ng of compressors and turbines, Off design performance. <u>After completion of this course students will be able</u> he working principles of turbomachines and apply it to va nachines | 8 Degree lations ooling | bours of reaction, Secondary of blades, K2 |
| Vortex Blades UNIT V Work done. V Zweifels relat flow, Free vor Actuator disc Performances Course out CO 1 H t | Axia Velocity ion, Des tex blad t, Theor , Matchi Come: Explain t ypes of 1 | Al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, D ign cascade analysis, Soderberg, Hawthrone, Ainley, Correl e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and c ng of compressors and turbines, Off design performance. <u>After completion of this course students will be able</u> he working principles of turbomachines and apply it to variable | 8 Degree lations ooling | of reaction, Secondary of blades, |

| | off-design conditions. | |
|---------------|--|---------|
| CO 4 | Analyse the design and calculate the design parameters for axial flow compressors. | K4 |
| CO 5 | Analyse the cascade design for axial flow gas turbines for various blades | K3, K4 |
| Reference | e Books | |
| (1) Principle | es of Turbo Machines/DG Shepherd / Macmillan | |
| (2)Fundame | entals of Turbomachinery/William W Perg/John Wiley & Sons | |
| (3)Element | of Gas Dynamics/Yahya/TMH | |
| (4) Principle | es of Jet Propulsion and Gas Turbine/NJ Zucrow/John Wiley & Sons/Newyo | ork |
| TextBook | (S | |
| (1) Turbines | s, Pumps, Compressors/Yahya/TMH | |
| (2)Practice | on Turbo Machines/ G.Gopal Krishnan &D.Prithviraj/ Sci Tech Publishers, | Chennai |
| (3)Theory a | nd practice of Steam Turbines/ WJ Kearton/ELBS Pitman/London | |
| <u> </u> | <u>^</u> | |

| | | M. TECH FIRSTYEAR | | | | |
|--|---|--|--|--|--|--|
| Cou | rse Code | AMTME0116 | LTP | Credit | | |
| Cou | rse Title | Advanced Mechanical Vibrations | 300 | 3 | | |
| Cou | rse objectiv | e: | | | | |
| 1 | | fferent types of vibration and mathematical ar | nalysis of single | degree | | |
| | | m under free vibration and damped vibration. | | 1.0 1 | | |
| 2 | | e analysis of two-degree freedom system under | · . | | | |
| 3 | | l principle and working of different types of vi y out exact and numerical analysis of multi de | | | | |
| 5 | subjected to different types of vibration. | | | | | |
| 4 | | e numerical methods to determine natural free | quencies of the b | beam and | | |
| | bar under free | and forced vibrations. | | | | |
| 5 | | e non-linear vibrating system under undamped | d and forced vib | oration. | | |
| | - requisites: knowledge of In | ndustrial engineering | | | | |
| | | Course Contents / Syllabus | | 0.1 | | |
| | | troduction | | 8 hours | | |
| | | racterization of engineering vibration problem | ns, Review of si | ingle degree | | |
| freed | lom systems wi | th free, damped and forced vibrations | | | | |
| UN | T-II T | wo-degree of Freedom Systems | | 8 hours | | |
| | | edom Systems: Principal modes of vibration | n Spring couple | | | |
| coup | - | prced vibration of an undamped close couple | | | | |
| Unda | amped vibration | n absorbers, Forced damped vibrations, Vibrat | - | ied systems, | | |
| | * | · · · | - | 8 hours | | |
| UNI | TIII M | n absorbers, Forced damped vibrations, Vibrat | tion isolation. | 8 hours | | |
| UNI Mult | IT III M ti-degree Free | n absorbers, Forced damped vibrations, Vibrat ulti-degree Freedom systems | tion isolation. | 8 hours | | |
| UNI Mult | IT III M ti-degree Free ems, Orthogona | n absorbers, Forced damped vibrations, Vibrat allti-degree Freedom systems edom systems: Eigen-value problem, Close | tion isolation. | 8 hours far coupled and forced | | |
| UNI Mult syste vibra | IT III M ti-degree Free ems, Orthogona ution systems, A | n absorbers, Forced damped vibrations, Vibrat Aulti-degree Freedom systems edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for | tion isolation. | 8 hours far coupled and forced , Dunkerely, | | |
| UNI Mult syste vibra Stode | IT III M ti-degree Free ems, Orthogona ution systems, A | n absorbers, Forced damped vibrations, Vibrat ulti-degree Freedom systems edom systems : Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite | tion isolation. | 8 hours far coupled and forced , Dunkerely, | | |
| UNI Mult syste vibra Stode coup | IT III M ti-degree Free ems, Orthogona ition systems, <i>A</i> ola and Holzer led and far cou | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close | | |
| UNI Mult syste vibra Stode coup | IT III M ti-degree Free ems, Orthogona ation systems, A ola and Holzer led and far cou IT-IV Co | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close 8 hours | | |
| UNI Mult syste vibra Stode coup UNI | IT III M ti-degree Free ems, Orthogona otion systems, A ola and Holzer Ition led and far cou IT-IV Co Co tinuous system | n absorbers, Forced damped vibrations, Vibrat ulti-degree Freedom systems edom systems : Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close 8 hours | | |
| UNI Mult syste vibra Stode coup UNI Cont force | IT III M ti-degree Free Free ems, Orthogona Stion systems, A ola and Holzer Idea and Holzer iled and far cou IT-IV IT-IV Co tinuous system Stinuous system | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequer r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars | tion isolation. e coupled and free, damped ncy- Rayleigh's, e element metho y wave equatio | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and | | |
| UNI Mult syste vibra Stode coup UNI Cont force | IT III M ti-degree Free Free ems, Orthogona Stion systems, A ola and Holzer Idea and Holzer iled and far cou IT-IV IT-IV Co tinuous system Stinuous system | n absorbers, Forced damped vibrations, Vibrat ulti-degree Freedom systems edom systems : Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by | tion isolation. e coupled and free, damped ncy- Rayleigh's, e element metho y wave equatio | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and | | |
| UNI Mult syste vibra Stode coup UNI Cont force | IT IIIMti-degreeFreeems,Orthogonaation systems,Aola and HolzerIdled and far couIT-IVIT-IVCotinuous systemcoed vibrations ofnsient Vibration | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequer r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and | | |
| UNI Syste vibra Stode coup UNI Cont force Trar | IT IIIMti-degreeFreeems,Orthogonaation systems,Aola and HolzerIled and far couIIT-IVCotinuous systemcoed vibrations ofasient VibrationTVNo | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse | tion isolation. e coupled and free, damped ncy- Rayleigh's, e element metho y wave equatio input, Shock sp | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and ectrum 8 hours | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI | IT IIIMti-degreeFreeems,Orthogonaution systems,Aola and HolzerIdled and far couIT-IVIT-IVCotinuous systemcoed vibrations ofnsient VibrationT VNo-linearVibration | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequer r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed b beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations | tion isolation. e coupled and free, damped ncy- Rayleigh's, e element metho y wave equatio input, Shock sp | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and ectrum 8 hours | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI Non- | IT IIIMti-degreeFreeems,Orthogonaution systems,Aola and HolzerIdled and far couIT-IVIT-IVCotinuous systemcoed vibrations ofnsient VibrationT VNo-linearVibration | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations ions: Non-linear systems, Undamped and matrix | tion isolation. e coupled and free, damped ncy- Rayleigh's, e element metho y wave equatio input, Shock sp | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and ectrum 8 hours | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI Non- linea | IT IIIMti-degreeFreeems,Orthogonaution systems,Aola and HolzerIdled and far couIT-IVIT-IVCotinuous systemcoed vibrations ofnsient VibrationT VNo-linearVibration | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations ions: Non-linear systems, Undamped and in Self-excited vibrations. | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and ectrum 8 hours n with non- | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI Non- linea | IT III M ti-degree Free ems, Orthogona ition systems, A ola and Holzer Ition and Holzer led and far cou Itinuous system IT-IV Co tinuous system Co ed vibrations of Isient Vibration r spring forces, Insee outcome | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations ions: Non-linear systems, Undamped and in Self-excited vibrations. e: After completion of this course stude | tion isolation. | 8 hours far coupled and forced Dunkerely, od for close 8 hours n, Free and ectrum 8 hours n with non- | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI Non- linea | IT III M ti-degree Free ems, Orthogona ation systems, A ola and Holzer Idea and far cou iled and far cou IT-IV Co tinuous system co ed vibrations of Isient Vibration r spring forces, Insee outcome 1 Demonstrat | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations ions: Non-linear systems, Undamped and in , Self-excited vibrations. e: After completion of this course stude | tion isolation. | 8 hours far coupled and forced and forced b Dunkerely, b for close 8 hours n, Free and ectrum 8 hours n with non- e to he K2, K3 | | |
| UNI Syste vibra Stode coup UNI Cont force Trar UNI Non- linea | IT III M ti-degree Free ems, Orthogona ation systems, A ola and Holzer Idea and far cou iled and far cou IT-IV Co tinuous system co ed vibrations of Isient Vibration r spring forces, Insee outcome 1 Demonstrat | n absorbers, Forced damped vibrations, Vibrat [ulti-degree Freedom systems] edom systems: Eigen-value problem, Close ality of mode shapes, Modal analysis for Approximate methods for fundamental frequent r method, Method of matrix iteration, Finite pled systems. ontinuous systems ns: Forced vibration of systems governed by beams/ bars ons: Response to an impulsive, step and pulse on-linear Vibrations ions: Non-linear systems, Undamped and re- , Self-excited vibrations. e: After completion of this course stude te the different types of vibration a cally the single degree freedom system under | tion isolation. | 8 hours far coupled and forced and forced b Dunkerely, b for close 8 hours n, Free and ectrum 8 hours n with non- e to he K2, K3 | | |

| | frequency for forced vibration of a two degree of freedom damped or | |
|--------|--|---------------------------------|
| | undamped system. | |
| CO 3 | Apply the mathematical analysis of multi degree freedom system | K_4, K_5 |
| _ | subjected to different types of vibration to calculate natural frequency. | ., . |
| CO 4 | Apply the numerical methods and calculate natural frequencies of the | K ₃ , K ₄ |
| | beam and bar under free and forced vibrations. | |
| CO 5 | Compute the natural frequencies of non-linear vibrating system under | K4 |
| | undamped and forced vibration. | |
| | | |
| | | |
| Text H | Books | |
| Theory | and practice of Mechanical Vibrations J.S. Rao and K. Gupta New Age Inter- | national |
| Mechar | nical Vibrations G.K. Groover Nem Chand & Brothers | |
| Mechar | nical Vibration Practice V. RamamurtiNarosa Publications | |
| Refer | enceBooks | |
| Mechar | nical Vibrations V.P. Singh Dhanpat Rai & sons | |
| | ok of Mechanical Vibrations R.V. Dukkipati& J. Srinivas Prentice Hall of Ind | lia |
| | <u> </u> | |

| | | M. TECH FIRST YEAR | |
|---|--|---|--|
| Co | ourse Code | AMTME0117 L T P | Credit |
| | ourse Title | Operations Research 3 0 0 | 3 |
| | URSE OBJECTI | | 5 |
| 1 | Ability to underst | and and analyze managerial problems in industry so that they are able to us ls, staffing, and machines) more effectively. | se resources |
| 2 | | mulating mathematical models for quantitative analysis of managerial prol | blems in |
| 3 | | f Operations Research approaches and computer tools in solving real prob | lems in |
| 4 | | dels for analysis of real problems in Operations Research. | |
| Pre | e-requisites | | |
| | 1 | Course content /syllabus | |
| Un | nit-1 Int | roduction 8 I | Hours |
| | | n and scope of OR; Techniques and tools; Model formulation; general of optimization problems; Optimization techniques. | l methods for |
| Un | nit-2 Lir | near Programming 8 H | Hours |
| Ass Inte | signment, transporta | fodels: Complex and revised simplex algorithms; Duality theorems, sensit ation and transhipment models; Traveling salesman problem as an Assignr c programming; Goal programming. Game Problems: Mini-max criterion zero sum game; Games by simplex dominance rules. | nent problem; |
| | | | Hours |
| exp | | ms: Classification of queuing situations; Kendall's notation, Poisson service time distribution; Finite and infinite queues; Optimal service rates adustrial problems. | |
| Uŋ | nit-4 Dy | namic Programming 8 I | Hours |
| | | g: Characteristic of dynamic programming problems (DPPs); Bellman's vith finite number of stages; Use of simplex algorithm for solving DPPs. | s principle of |
| | | | Hours |
| UN | | | Ivais |
| Nor Opt | 0 | ing: One dimensional minimization method; Unconstrained optimization uses characteristics of a constrained problem; Indirect methods; Search | n techniques; |
| Nor Opt met | timization technique thods. | es characteristics of a constrained problem; Indirect methods; Search | n techniques; and gradient |
| Nor Opt met | timization techniqu hods. C ourse Outcome | nes characteristics of a constrained problem; Indirect methods; Search s: -After the successful completion of the course, the students will be a | n techniques; and gradient ble to: |
| Nor Opt met | timization technique thods. Course Outcome understand the a build and solve | es characteristics of a constrained problem; Indirect methods; Search | n techniques; and gradient ble to: K2 |
| Nor Opt met | timization technique thods. Course Outcome understand the a build and solve method. | es characteristics of a constrained problem; Indirect methods; Search s: -After the successful completion of the course, the students will be al pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria | n techniques; and gradient ble to: K2 ate K3 |
| Nor Opt met | timization technique thods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- | as characteristics of a constrained problem; Indirect methods; Search s: -After the successful completion of the course, the students will be al pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria waiting line problems using appropriate method. oblems of replacement and implement practical cases of decision making | ble to: K2 Ate K3 K3 |
| Nor Opt met 1 2 3 | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- | s: -After the successful completion of the course, the students will be al pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria | ble to: K2 ate K3 K3 K4 |
| Nor Opt met 1 2 3 4 5 | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- | es characteristics of a constrained problem; Indirect methods; Search s: -After the successful completion of the course, the students will be al pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria waiting line problems using appropriate method. oblems of replacement and implement practical cases of decision making usiness environments. bblems of unconstrained nonlinear programming. Knows the necessary a | ble to: K2 ate K3 K3 K4 |
| Nor Opt met 1 2 3 4 5 | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- sufficient condit kt Books | s: -After the successful completion of the course, the students will be all pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria waiting line problems using appropriate method. oblems of replacement and implement practical cases of decision making usiness environments. oblems of unconstrained nonlinear programming. Knows the necessary a ions for the solution of unconstrained problems. | ble to: K2 ate K3 K3 K4 |
| Nor Opt <u>(1</u> 2 3 4 5 Tex | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- sufficient condit xt Books Operations Res | earch, H.A. Taha, Prentice Hall | ble to: K2 ate K3 K3 Mg K4 |
| Nor Opt met 1 2 3 4 5 Tex 1 2 | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- sufficient condit xt Books Operations Res | s: -After the successful completion of the course, the students will be all pplication of OR and frame a LP Problem with solution – graphical. Transportation, Assignment and Game Model problems using appropria waiting line problems using appropriate method. oblems of replacement and implement practical cases of decision making usiness environments. oblems of unconstrained nonlinear programming. Knows the necessary a ions for the solution of unconstrained problems. | ble to: K2 ate K3 K3 Mg K4 |
| Nor Opt met 1 2 3 4 5 Tex 1 2 | timization technique hods. Course Outcomes understand the a build and solve method. build and solve v solve simple pro- under different b analyses the pro- sufficient condit kt Books Operations Res Engg. Optimiza ference Books | earch, H.A. Taha, Prentice Hall | ble to: K2 ate K3 K3 Mg K4 |

| | | M. TECH FIRST Y | EAR | |
|---------|-----------------------|---|--------------------------|---------------------------------|
| Cour | se Code | AMTME0118 | L T P | Credit |
| Cour | se Title | Advanced I.C. Engines | 3 0 0 | 3 |
| Cour | se objectiv | e: | | |
| 1 | | and classify conventional, modern eng | gine technologies of I. | C. Engines. |
| 2 | To discuss a | and analyze various combustion pheno | | |
| | | nes and C.I. Engines. | | |
| 3 | | competence in performance analysis, | optimization, and cont | trol of IC |
| 4 | engines. | an insight about fuels, alternatives fue | la effect of engine ou | |
| 4 | | an insight about fuels, alternatives fue nent and emission control methods. | ers, effect of engine ou | temissions |
| 5 | | skill and acquire knowledge of moder | n engine technologies | and develop |
| 5 | | mobility solutions. | in engine teennologies | und de velop |
| Pre-r | equisites: | | | |
| | | ndustrial engineering | | |
| | | Course Contents / Syl | labus | |
| UNIT | [-] Ir | ntroduction | | 8 hours |
| Introdu | uction to diff | erent types of conventional and mode | rn I.C. Engine, Valve | arrangements, |
| | l cycles for er | • • | | |
| UNI | Г-II С | ombustion of engines | | 8 hours |
| Comb | ustion in CI & | & SI engines, Knocking parameters, C | ombustion chambers c | onstruction |
| | | esting and performance nance, Engine cooling & lubrication, ntrol. | , Effects of Superchar | 8 hours |
| UNIT | Γ-IV F | uels | | 8 hours |
| | - | f fuels, Rating of fuels, Alternative f gines, pollution control devices, Blue | | & lubrication, |
| UNIT | V M | lodern Technology | | 8 hours |
| Stratif | ied-charged | Engine, Marine & Aerospace eng | ines, Mixed-cycle er | ngines, HCCI |
| Engine | es, GDI Tec | hnology, E-Turbocharger, Variable | compression ratio en | gines, Hybrid |
| Engine | es, Hydrogen | and Fuel Cell Technology. Hybrid | power train concepts | s and designs |
| (series | , parallel). | | | |
| Cour | se outcome | e: After completion of this cour | se students will be ab | le to |
| CO | 1 Explain technolo | | and modern engine | K2, K3 |
| CO | 2 Explain | and understand the gas exchange pro | ocesses and motion of | K ₃ , K ₄ |
| | charge i and CI e | n the cylinder and its effects on com | bustion process in SI | |
| CO | | the performance, optimization, and c | ontrol of I.C. engines. | K4, K5 |
| CO | 4 Express treatmen | the fuels, alternatives fuels, emission | s formation and their | K _{3,} K ₄ |

| CO 5 | Explain and demonstrate modern engine technologies and develop smart future mobility solutions. | K4 | | | |
|-----------|---|------------|--|--|--|
| | | | | | |
| Text Bo | oks | | | | |
| I.C Engin | I.C Engine Analysis & Practice by E.F Obert. | | | | |
| I.C Engin | e by Ganesan, Tata McGraw Hill Publishers. | | | | |
| A Course | in International Combustion Engines, by Mathur& Sharma, DhanpatR | ai& Sons. | | | |
| Referen | ceBooks | | | | |
| I.C Engin | e, by R. Yadav, Central Publishing House, Allahabad | | | | |
| Reciproca | ting and Rotary Compressors, by Chlumsky, SNTI Publications, Czec | hoslovakia | | | |
| Engineeri | ng Fundamentals of Internal Combustion Engines by W.W. Pulkrabek | , Pearson | | | |

| M. TECH FIRST YEAR | | | | | |
|--------------------------|---------------------------------|---|-------------------------|---------------------------|--|
| Cou | rse Code | AMTME0201 | LTP | Credit | |
| Cou | rse Title | Digital Manufacturing and Automation (DMA) | 3 0 0 | 3 | |
| Cou | rse objecti | ve: | | | |
| 1 | | ding of the Development of CNC Technology and Industr | ry 4.0 | | |
| 2 | Learning a & 3-D prir | bout the CNC Programming, G & M Codes, CAM packa ating. | ges, Geometr | ical Design | |
| 3 | Smart man | e a detailed interpretation of Tooling for CNC Machines, ufacturing. | • | | |
| 4 | Learning a | bout Robotics and Material Handling Systems, Automate | ed guided veh | icle systems. | |
| 5 | | bout the Group Technology and FMS, Understanding and Concurrent engineering. | d Learning ab | out the CIM | |
| Pre- | | Basics of Manufacturing | | | |
| | 1 | Course Contents / Syllabus | | | |
| UNI | T-I | Introduction to CNC Machine Tools: | | 6 hours | |
| | | NC Technology-Principles and classification of CNC ma | chines, Adva | | |
| | * | , Types of control, CNC controllers, Characteristics, Inter | | • | |
| | concept. Ind | | | | |
| UNI | T-II | CNC Programming: | | 8 hours | |
| Co-or | rdinate Syste | m, Fundamentals of APT programming, Manual part prog | gramming-str | ucture of | |
| part p | orogramme, O | G & M Codes, developing simple part programmes, Paran | netric prograr | nming, | |
| | | r CNC machines-IDEAS, Unigraphics, Pro Engineer, CA | | | |
| | | e of standard controllers-FANUC, Heidenhain and Sinum | eric control s | ystem. | |
| | | gn. 3-D printing. | | 1 | |
| | T-III | Tooling for CNC Machines: | | 6 hours | |
| coolin turnir | ng fed tooling | ials, Carbide inserts classification; Qualified, semi qualif g system, Quick change tooling system, Tooling system f l holders, Tool assemblies, Tool magazines, ATC mecha- ing. | or machining | centre and | |
| UNI | T-IV | Robotics and Material Handling Systems: | | 8 hours | |
| Introd Types Autor | duction to rol s of material | potic technology, and applications, Robot anatomy, mater handling equipment, Conveyer systems, Automated guid e/retrieval systems, Work-in-process storage, Interfacing | ed vehicle sys | unction, stems, | |
| UNI | T-V | Group Technology and Flexible Manufacturing S | System: | 12 hours | |
| | | y-part families, Parts classification and coding, Production | • | | |
| | • | fits of Group Technology, Flexible manufacturing system | | on, FMS | |
| | | nputer control system, Planning for FMS, Applications ar | | D ¹ 1 1 | |
| | | ated Manufacturing: Introduction, Evaluation of CIM a | | | |
| | - | d Automation (DMA), CIM hardware and software, Requ | | - | |
| | | stem, Database requirements, Concurrent Engineering-Pr | incipies, desi | gn and | |
| | | ronment, advance modelling techniques. | -hl. () | | |
| Cou | rse outcon | 1e: Upon completion of the course, the student will be | able to: | | |
| CO 1 | | nd the Development of CNC Technology- C istics, Interpolators, Applications, DNC concept and Indu | CNC control stry 4.0 | llers, K ₂ | |

| CO 2 Learned about the CNC Programming, G & M Codes, CAM packages, Geometrica | K ₃ |
|---|------------------|
| Design & 3-D printing. | |
| CO 3 Use detailed interpretation of Tooling for CNC Machines, Cutting tool materials, & | K3 |
| Smart manufacturing. | |
| CO 4 Know about Robotics and Material Handling Systems, Robot anatomy, Conveye | · K5 |
| systems, Automated guided vehicle systems, Interfacing handling and storage with | L |
| manufacturing. | |
| CO 5 Apply detailed interpretation of the GT and FMS, CIM, requirements of computer to | • K ₆ |
| be used in CIM and DMA, Concurrent engineering. | |
| Text books | |
| 1. Computer Numerical Control Machines P. Radhakrishnan New Central Book Agency | |
| 2. CNC Machines M.S. Sehrawat and J.S. Narang Dhanpat Rai and Co. | |
| 3. CNC Programming Handbook Smid Peter Industrial Press Inc. | |
| Reference Books | |
| 1. Automation, Production systems and Computer M.P. Groover Prentice Hall of India I | ntegrated |
| Manufacturing | 5 |
| 2. Computer Integrated Manufacturing Paul Ranky Prentice Hall of India | |
| | |

| | | M. TECH FIRST YEAR | | |
|--|--|--|---|---|
| Course Co | de | AMTME0202 | LTP | Credit |
| Course Tit | tle | Composite Materials | 300 | 3 |
| Course ob | jective: | | | |
| 1 7 | To understa | and Composite materials and its applications. | | |
| 2 7 | To understa | and the various types of composite materials | | |
| 3 7 | To know th | e processing techniques of composite materials | | |
| 4 I | Determine | stresses and strains in composites. | | |
| 5 U | Understan | d the mechanical behaviour of laminated composi | te | |
| Pre-requise materials | ites:The | student should have knowledge of material scie Course Contents / Syllabus | ence and s | strength of |
| UNIT-I | Int | roduction to composites | 8 h | ours |
| Functions of Thermoplast Reinforceme fibres, Carbo carbide fibre properties of | a Matrix ics), Meta nts/fibres: on fibres, s, Quartz f fibres. | ineering Materials, Concept of composite materia , Desired Properties of a Matrix, Polymer Mat 1 matrix, Ceramic matrix, Carbon Matrix, Glass Role and Selection or reinforcement materials, T Aramid fibres, Metal fibres, Alumina fibres, Fla and Silica fibres, Multiphase fibres, Whiskers, Fla Material properties that can be improved by for ering potential. | rix (Therr Matrix etc Ypes of fi Boron fibr Ikes etc., N | nosets and c. Types of bres, Glass es, Silicon Mechanical |
| UNIT-II | Cla | ssification of composites: | 8 h | ours |
| composites (composites (Classificatio Polymer (FR | PMC), Ca MMC), C n based P) Compo | on Matrix Material: Organic Matrix compositions on matrix Composites or Carbon-Carbon Composites (CMC); on reinforcements: Fibre Reinforced Composite posites, Laminar Composites, Particulate Composite limitations of Composites | posites, M es, Fibre | etal matrix Reinforced |
| UNIT-III | FA | BRICATION OF COMPOSITES | 8 h | ours |
| Autoclave c | | s: Processing of Composite Materials: Ove | erall cons | iderations |
| Combined I materials, Re bagging film Nano Comp industrial app UNIT-IV Mechanical fraction. Uni | Fibre-Matricelease age sosite: Introduction of Properties directiona | ther Manufacturing Processes like filament we splant method, pultrusion, pre-peg layer, F rix performs, Manufacturing Techniques: Too ents, Peel plies, release films and fabrics, Bleede troduction to Nano Composites, Processing of finano composites. Perties of Composites a -Stiffness and Strength: Geometrical aspects – al continuous fibre, discontinuous fibres, Short fibres, Composites, Short fibres, Testing: Determination of stiffness | ibre-only oling and or and brea of nano c 8 h volume a ibre system | ompression performs, Specialty ather plies, omposites, ours and weight ms, woven |
| Combined I materials, Re bagging film Nano Comp industrial app UNIT-IV Mechanical fraction. Uni reinforcemen | resin-trans Fibre-Matrelease age sosite: Interplication of Properties directionants –Mecondi composition | pplant method, pultrusion, pre-peg layer, F rix performs, Manufacturing Techniques: Too ents, Peel plies, release films and fabrics, Bleede troduction to Nano Composites, Processing o of nano composites. perties of Composites a -Stiffness and Strength: Geometrical aspects – | ibre-only oling and or and brea f nano c 8 h volume a ibre system and str | ompression performs, Specialty ather plies, omposites, ours and weight ms, woven |

Plate Stiffness and Compliance, Assumptions, Strains, Stress Resultants, Plate Stiffness and Compliance, Computation of Stresses, Types of Laminates -, Symmetric Laminates, Antisymmetric Laminate, Balanced Laminate, Quasi-isotropic Laminates, Cross-ply Laminate, Angleply Laminate. Orthotropic Laminate, Laminate Moduli, Hygrothermal Stresses

| Course outcome: After completion of this course students will be able to | | | | | |
|---|---|---------------------------------|--|--|--|
| CO 1 | Understand various matrices and reinforcements used in composites | K ₂ , K ₃ | | | |
| CO 2 | Know about polymer matrix composites, metal matrix composites, ceramic matrix composites and its manufacturing and applications | K3 | | | |
| CO 3 | Introduce Fabrication techniques of composites | K3 | | | |
| CO 4 | Determine stresses and strains in composites. | K4 | | | |
| CO 5 | Understand the specifics of mechanical behaviour of layered | K4, K5 | | | |
| | composites compared to isotropicmaterials | | | | |
| Text bo | ooks | | | | |
| R. M. Joi | R. M. Jones, Mechanics of Composite Materials, CRC Press | | | | |
| M. Mukh | opadhyay, Mechanics of Composite Materials, University Press | | | | |
| I. S. Dan Press | I. S. Daniel and Ori Ishai, Engineering Mechanics of Composite Material, Oxford University Press | | | | |
| Referen | ice Books | | | | |
| K K Chawla, Fibrous Materials, Cambridge University Press. | | | | | |
| Thermal | Analysis of Materials by R.F. Speyer, Marcel Decker. | | | | |
| Engineer India. | Engineering Materials: Polymers, Ceramics and Composites A.K Bhargava Prentice Hall India. | | | | |

| | | M. TECH FIRST YEAR | | | | |
|------|-------------------------------|--|----------------|-------------|--|--|
| Cour | Course Code AMTME0251 LTP Cre | | | | | |
| Cour | se Title | Automation and Mechatronics Lab | 0 0 4 | 2 | | |
| Cour | se objectiv | | | | | |
| 1 | - | he knowledge on advanced algebraic tools for the c | - | | | |
| 2 | - | he ability to analyze and design the motion for arti | • | | | |
| 3 | To develop a | n ability to use software tools for analysis and des | ign of robot | ic systems. | | |
| | | List of Experiments | | | | |
| 1 | machine. | out workpiece setting and coordinate setting on V | ertical Millin | ng | | |
| 2 | Surface ope | ration on Vertical Milling Machine. | | | | |
| 3 | Machining | operation using canned cycle on Milling Machine. | | | | |
| 4 | Learning al | pout workpiece setting and coordinate setting on T | urning Cent | er. | | |
| 5 | Performing | Machining operation like Turning, Slotting, Facin | g. | | | |
| 6 | | operation using canned cycle and Threading on La | the machine | • | | |
| 7 | | ace Operation on Kuka Kr-10 robot. | | | | |
| 8 | - | welding operation using Kuka Kr-10 robot. | | | | |
| 9 | | controller (Arduino/ Raspberry) | | | | |
| 10 | Controller in | nterfacing. ((Arduino/ Raspberry). | | | | |
| Cour | se outcome | e: After completion of this course students | will be able | to | | |
| CO1 | Set machi | ne coordinate and perform machining operations. | | K3 | | |
| CO2 | Program r | obot and perform operations on it. | | K4 | | |
| CO3 | Design a d | controller (Arduino/ Raspberry) and programme it. | | K3 | | |
| CO4 | Interface t | he controller with machine. | | K4 | | |

| Cou | rse Code | AMTME0252 | L T P | Credit |
|-------|--------------|---|-------------------|----------------|
| Cour | rse Title | Composite Materials Lab | 0 0 4 | 2 |
| Cour | rse objectiv | ve: | · | • |
| 1 | | and the metal matrix composite. | | |
| 2 | | and the various types of reinforcement. | | |
| 3 | | ne powder metallurgy techniques. | | |
| 4 | | e stresses and strains in composites. | | |
| 5 | Understan | d the mechanical behaviour of laminated comp | posite | |
| | | List of Experiments | | |
| 1 | Preparation | n of Metal matrix Composites. | | |
| 2 | Preparation | n of surface composite by friction stir processir | ıg | |
| 3 | Study of To | ensile strength and young's modulus of MMCs | • | |
| 4 | | model on 3D printer by using glass fiber as a r erial of nylon. | einforcement m | aterial into a |
| 5 | Preparation | n of composite by powder metallurgy technique | es. | |
| 6 | Study of Fl | lexural strength of MMCs. | | |
| 7 | Study of H | ardness of MMCs. | | |
| 8 | Impact stre | ength analysis of MMCs | | |
| 9 | Preparation | n of Al-SiC composites by stir casting method. | | |
| 10 | - | icrostructure, hardness and density of Al-SiC of | composite | |
| | <u> </u> | - | * | |
| Cou | rse outcom | e: After completion of this course stude | ents will be able | e to |
| (| CO1 Pr | repare metal matrix composite. | | K2 |
| CO1 D | | | | 1/2 |

| CO1 | Prepare metal matrix composite. | K2 |
|-----|---|----|
| CO2 | Demonstrate the friction stir processing. | K3 |
| CO3 | Demonstrate the powder metallurgy techniques. | K3 |
| CO4 | Determine stresses and strains in composites. | K2 |

| | | M. TECH FIRST YEAR | | | | |
|------------------|--|---|---|--|--|--|
| Cou | rse Code | AMTME0211 | LTP | Credit | | |
| Cou | rse Title | Advanced Finite Element Analysis | 300 | 3 | | |
| Coui | rse Objective | es: The students should be able to | | | | |
| 1 | Understand the fundamental concepts and different approaches used in Finite Element method. | | | | | |
| 2 | axi-symmet | I the application of plane stress- strain problem and use of t tric, heat transfer and fluid flow problems. | | | | |
| 3 | plane eleme | | | | | |
| 4 | Understand | d and demonstrate the mesh generation used in FEA analysis | s for design and eva | luation | | |
| 5 | Understan | d and command the practical application of finite elements ag problems through the use of FEM packages software. | nt method to solve | e realistic | | |
| l | UNIT-I I | Introduction to Finite Difference Method | | 8HOUR | | |
| 1 (| Natural co-or Convergence | l formulation of FEM, Variational and Weighted residu rdinate system, Element and global stiffness matrix and patch test, Higher order elements. | , Boundary con | ditions, Erro | | |
| 1 | UNIT-II | Application to plane stress and plane strain problems | 5 | 8 HOUF | | |
| | Application to plane stress and plane strain problems, Axi-symmetric and 3D bodies, Plate be problems with isotropic and anisotropic materials, Structural stability, Other applications e.g., conduction and fluid flow problems. | | | | | |
| - | | · · | ty, Other applica | tions e.g., H | | |
| Ċ | conduction ar | · · | ty, Other applica | tions e.g., H | | |
| l I | conduction arUNIT-IIIIdealization | nd fluid flow problems. | | 8 HOUR | | |
| c l l r | conduction ar UNIT-III I Idealization c naterially | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, | | 8 HOUR | | |
| | conduction arUNIT-IIIIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealizationIdealization | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems | , Applications of | 8 HOUE the method 8 HOUE | | |
| | conduction ar UNIT-III Idealization Idealization Idealization UNIT-IV Organization computer grap | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation | , Applications of | 8 HOUF the method 8 HOUF | | |
| | conduction arUNIT-IIIIIdealizationIIdealizationIIdealizationIUNIT-IVIOrganizationIcomputer gragIUNIT-VIFEM an esser | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation phics, Numerical techniques, 3D problems | Applications of | 8 HOUE the method 8 HOUE eration throu 8 HOUE | | |
| | conduction arUNIT-IIIIdealizationIdealizationIdealizationIdealizationUNIT-IVOrganizationcomputer grayUNIT-VIFEM an essenexisting comp | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation phics, Numerical techniques, 3D problems FEM an essential component of CAD ntial component of CAD, Use of commercial FEM pac | Applications of | 8 HOUE the method 8 HOUE eration throu 8 HOUE | | |
| | conduction ar UNIT-III I Idealization c idealization c unitrily o UNIT-IV O Organization c computer gray unitriv UNIT-V I FEM an esser existing comp Course Outco Appl | nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation phics, Numerical techniques, 3D problems FEM an essential component of CAD ntial component of CAD, Use of commercial FEM pac- plete designs, Comparison with conventional analysis. | , Applications of n and mesh gene kages, Finite elen | 8 HOUF the method 8 HOUF eration throu 8 HOUF nent solution | | |
| | conduction ar UNIT-III I Idealization c idealization c idealization c uniterially non i UNIT-IV I Organization c computer grap i UNIT-V I FEM an essen c existing comp c Course Outcourse CO1 Appl probl Appl CO2 symm | Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation phics, Numerical techniques, 3D problems FEM an essential component of CAD ntial component of CAD, Use of commercial FEM pac- plete designs, Comparison with conventional analysis. | Applications of n and mesh gene kages, Finite elen ve realistic engir global equation f | 8 HOUF the method 8 HOUF eration throut 8 HOUF nent solution neering K2, for axi- K3 | | |
| | conduction ar UNIT-III I Idealization contaction idealization contaction unit-IV I Organization computer gray UNIT-IV I FEM an esser existing comp Course Outco CO1 Appl probl CO2 symm strain CO3 Appl | Idealization of stiffness of stiffness of beam elements in beam-slab problems, n-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparation phics, Numerical techniques, 3D problems FEM an essential component of CAD ntial component of CAD, Use of commercial FEM pace plete designs, Comparison with conventional analysis. comes: The students would be able to ly the fundamental concepts and approaches to solv lems. y the fundamental concepts of boundary conditions to metric, heat transfer and fluid flow problems and solve those | Applications of n and mesh gene kages, Finite elen ve realistic engir global equation f e displacements, str | 8 HOUF the method 8 HOUF eration throut 8 HOUF enent solution neering K2, for axi- ess and K3 | | |

| | Develop proficiency in the application of the finite element method (modelling, analysis, | K4, K5 |
|-----|---|--------|
| CO5 | and interpretation of results) to realistic engineering problems through the use of a major | |
| | commercial general-purpose finite element code. | |

| Tex | t Books |
|------|--|
| 1 | The Finite Element Method O.C. Zienkiewicz and R.L. Taylor McGraw Hill |
| 2 | An Introduction to Finite Element Method J. N. Reddy McGraw Hill |
| 3 | Finite Element Procedure in Engineering Analysis K.J. Bathe McGraw Hill |
| 4 | Finite Element Analysis C.S. Krishnamoorthy Tata McGraw Hill |
| Refe | erences Books: |
| 1 | Concepts and Application of Finite Element Analysis R.D. Cook, D.S. Malcus and M.E. Plesha John Wiley |
| 2 | Introduction to Finite Elements in Engineering T.R Chandragupta and A.D. Belegundu Prentice Hall India |
| 3 | Finite Element and Approximation O.C. Zenkiewicy& Morgan |

| | | M. TECH FIRST YEAR | | |
|---------------|-----------|--|--------------|---------------|
| Course Cod | le | AMTME0212 | LTP | Credit |
| Course Title | e | Modern Manufacturing Technology | 300 | 3 |
| Course obje | ective: | | •••• | |
| | | stand the non-traditional manufacturing process | | |
| | | stand the concept of ultrasonic machining. | | |
| | | be the electrical discharge machining | | |
| | | be the electrochemical machining and hybrid machin | ing | |
| | | stand the unconventional welding and forming. | 0 | |
| Pre-requis | | | | |
| | | Course Contents / Syllabus | | |
| UNIT-I | | Introduction: | | 7 hours |
| Need of No | on-Tradi | tional Machining Processes, ClassificationBased of | on Energy, | Mechanism |
| source of en | nergy, tr | ansfer media and process, Process selection Based | on Physica | l Parameters |
| shapes to be | machine | ed, process capability and economics, Overview of all | processes. | |
| UNIT-II | | Ultrasonic Machining | | 8 hours |
| Ultrasonic | Machin | ing: Principle- Transducer types, Concentrat | tors, Abra | asive Slurry |
| ProcessPara | meters, ' | Tool Feed Mechanism, Advantages and Limitations | , Applicati | ons. Abrasive |
| Jet Machinin | ng: Proc | ess- Principle, Process Variables – Material Remov | al Rate, Ac | lvantages and |
| Limitations, | Applica | tions. Water Jet Machining: Principle, Process Va | riables, Ad | lvantages and |
| Limitations, | Practica | lApplications, Abrasive water jet machining process | • | |
| UNIT-III | | Electrical Discharge Machining | | 8hours |
| Electrical Di | ischarge | Machining: Mechanism of metal removal, Dielectric | Fluid, Flus | hingmethods |
| Electrode M | aterials, | Spark Erosion Generators, Electrode Feed System, | Material R | emoval Rate |
| ProcessPara | meters, ' | Tool Electrode Design, Tool wear Characteristics of | Spark Ero | ded Surfaces- |
| | | itations, Practical Applications. Electrical Discharge | | |
| Principle, W | Vire Fee | d System, Advantages and Limitations - Practica | al applicati | ons, Electror |
| | ining, pl | asma arc machining, laser beam machining | | |
| UNIT-IV | | Chemical, Electrochemical and Hybrid Machir | ning | 8 hours |
| | | Process | | |
| | | Process: material removal mechanism, process para | | |
| | | achining process: Material Removal Mechanism | n, process | parameters |
| applications, | | | 1 1. | |
| | | process: principle of unconventional hybrid | d machin | ing process |
| | ical grin | ding, electrochemical spark machining. | | |
| UNIT-V | | Advanced Welding and forming Techniques | | 8 hours |
| | | xplosive welding, Diffusion bonding, High freque | | tion welding |
| | • | Electron beam welding, Plasma arc welding, Laser w | • | 1. C . |
| | | energy rate forming, explosive forming, ele | ectrohydrau | llic forming |
| electromagn | ette torn | ning, incremental forming processes. | | |
| Course ou | tcome | After completion of this course students will | be able to | |
| CO 1 | underst | and the concepts of modern manufacturing technolog | gy | K1,K2 |
| CO 2 | Apply | the concept of mechanical processes such as | ultrasonic | K3, K4 |

| | machining, AJM,WJM | |
|--------|--|------------|
| CO 3 | Understand the concept of electrochemical machining process. | |
| CO 4 | Understand the concept of unconventional welding processes. | K3, K4, K5 |
| CO 5 | Apply the concept of unconventional metal forming process. | K3,K4 |
| Books: | | |

1. P.C Pandey And H.S. Shan, "Modern Machining Process", Tata Mc Graw – Hill Publishing Company Limited, New Delhi, 2007.

2. V.K. Jain, "Advanced Machining Process", Allied Publishers Pvt Limited 200.

3. Amitabha Bhattacharyya, "New Technology", The Institution of Engineers, India

4. HMT Bangalore, "Production Technology", Tata Mc Graw–Hill Publishing Company Limited, New Delhi, 2006.

5. Hassan El – Hofy "Advanced machining Processes" MC Graw-Hill, 2005.

| | | M. TECH FIRST YEAR | | | |
|---|--------------|---|------------|-------------|--|
| Cours | se Code | AMTME0213 | LTP | Credit | |
| Cours | se Title | Advanced Welding Technology | 300 | 3 | |
| | se objectiv | | | | |
| 1 | | | | | |
| | | in engineering industry applications. | | | |
| 2 | | erstanding of heat flow and temperature distribution of | on weld c | omponents | |
| | | eld geometry | | - | |
| 3 | | the knowledge on the design of welded joints and the | quality co | ontrol of | |
| | weldments. | | | | |
| 4 | * | knowledge and to solve problems associated with failu | | * | |
| | | the latest technology to ensure welded structure are m | aintained | in good | |
| 5 | | ondition and at low maintenance cost. nowledge on robotic welding systems as well as learn | how to p | arform | |
| 5 | | lures on a system. | now to p | CHOIIII | |
| Pro_r | equisites: | | | | |
| 110-1 | equisites. | Course Contents / Syllabus | | | |
| UNIT | TI Wal | Ŷ. | | 1 hours | |
| | | ding Metallurgy: | <u> </u> | 4 hours | |
| | | ed with other fabrication processes, Classification of | | | |
| | | e and its characteristics; Effects of alloying eleme | | | |
| | • | els, stainless steel, cast iron, and aluminum and tita | | | |
| testing | standards, | Hydrogen embrittlement, Lamellar tearing, residu | al stress | es and its | |
| measu | rement, heat | transfer and solidification, Analysis of stresses in we | elded stru | ctures, Pre | |
| and po | st welding h | eat treatments, Metallurgical aspects of joining, Con- | ditions of | soldering, | |
| | | g of materials | | 0 | |
| UNIT | -II Wel | d Design & Quality Control: | | 12 hours | |
| Weldir | | red with other fabrication processes, Classification of | f welding | processes; | |
| | | e and its characteristics; Effects of alloying eleme | | | |
| | | els, stainless steel, cast iron, and aluminium and tit | | | |
| | • | Hydrogen embrittlement, Lamellar tearing, residu | | • | |
| | | transfer and solidification, Analysis of stresses in we | | | |
| | | eat treatments, Metallurgical aspects of joining, Con- | | | |
| | | g of materials. | | solucing, | |
| UNIT | - | lern Trends in Welding: | | 8 hours | |
| | | xplosive welding, Diffusion bonding, High frequency | v inductio | | |
| | | Electron beam welding, Plasma arc welding, Laser w | | n weiding, | |
| UNIT | | air Welding and Reclamation: | | 8 hours | |
| | | ts of repair, aspects to be considered for repai | r weldin | | |
| | | | | | |
| economics, repair welding procedures for components made of steel casting and cast iron, half bead, temper bead techniques, usage of Ni base filler metals. Types of wear, wear | | | | | |
| resistant materials, selection of materials for various wear applications; reclamation | | | | | |
| | | s, selection of welding process for reclamation | , 1 | | |
| UNIT | | tics in Welding: | | 8 hours | |
| | | applications in welding, Programming of welding ro | | | |
| | | t welding, New generation of welding robots, Self-a | | | |
| | | oots for car body welding, Microelectronic weld | | | |
| - | , | | 0 | 0, | |

Efficiency of robotics in welding.

| CO 1 | Identify and understand the concepts of welding | K1,K2 |
|-------|---|---------------|
| CO 2 | Analyze peak temperatures, HAZ stresses and to prevent distortions | K3, K4 |
| CO 3 | Analyze and predict the life of weld joints subjected to fatigue and evaluate the effect of stress concentration on fatigue life of such joints. | K4 |
| CO 4 | Selection of repair welding and apply techno-economics for practical problems. | K3, K4, K5 |
| CO 5 | Use appropriate safety precautions while programming and operating the robot system | K3,K4 |
| Books | | |

1. Advanced Welding Processes Nikodaco&Shansky MIR Publications

2. Welding Technology and Design VM Radhakrishnan New Age International

3. Source Book of Innovative welding Processes M.M. SchwarizAmerican Society of Metals (Ohio)

4. Advanced Welding Systems, Vol. I, II, III J. CornuJaico Publishers

5. Manufacturing Technology (Foundry, Forming and Welding) P.N. Rao Tata McGraw Hill

6. Welding principles and practices by Edward R. Bohnart, Mc. Graw Hill Education, 2014.

7. Welding and Welding technology, Richard L little, Mc. Graw Hill Education

8. Welding processes and Technology – Dr.ParmarRS

9. Welding processes and Technology – O.P Khanna

10. Foundry, Forming and Welding, P.N.Rao 2nd Edition TMH

| | | M. TECH FIRST YEAR | | |
|---|---|---|---------------------------|---|
| Cour | se Code | AMTME0214 | LTP | Credit |
| Cour | se Title | Computational Fluid Dynamics (CFD) | 3 0 0 | 3 |
| Cours | e objective: | | | · |
| This co | ourse enable | s students to | | |
| 1. | | rovide brief introduction of Computational Fluid Dyn sis of fluid mechanics and heat transfer related problem | | hed with the |
| | | Course Contents / Syllabus | | |
| UNIT | -I INT | RODUCTION | | 8 hours |
| Introd | uction. Cons | ervation equation, Mass Momentum and Energy | equations. | |
| | | on and general description. | 1 , | |
| UNIT | | ndary and initial conditions | | 8 hours |
| | | various types of equation, Parabolic, Elliptic, | Boundary | and initial |
| | | ew of numerical methods | | |
| UNIT | -III Fini | e difference methods | | 8 hours |
| UNIT- Solutio | -IV Solu | surface treatment, Accuracy of F.D. method. tion of finite difference equations difference equations; Iterative methods; Matrix in | version me | 8 hours |
| | | plitting, Fast Fourier Transform applications | | thods, AD |
| UNIT | -V Phas | | | |
| Phase | change pro | e change problems | | 8 hours |
| functio | | te change problems plems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method | ase change | 8 hours nterpolation problems |
| functio | | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method | ase change | 8 hours nterpolation problems |
| functio Differe | ent approach Course Ou | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method | ase change | 8 hours nterpolation problems |
| functio Differe | ent approach Course Ou Understand | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method atcome: | ase change | 8 hours nterpolation problems method. |
| function Differed CO1 CO2 | ent approach Course Ou Understand Apply boun | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method itcome: the various governing equations related to CFD. | ase change d, Enthalpy | 8 hours nterpolation problems method. |
| function Differed CO1 CO2 CO3 | ent approach Course Ou Understand Apply boun Apply Finit | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method tecome: the various governing equations related to CFD. dary condition & initial conditions. | ase change d, Enthalpy | 8 hours nterpolation problems method. K2 K3 |
| function Different CO1 | ent approach Course Ou Understand Apply boun Apply Finit Evaluate the | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method attome: the various governing equations related to CFD. dary condition & initial conditions. e Difference and Finite Volume methods in CFD model | ase change d, Enthalpy | 8 hours nterpolation problems; method. K2 K3 K3 |
| CO1 CO2 CO3 CO4 CO5 | ent approach Course Ou Understand Apply boun Apply Finit Evaluate the Understand of Authors | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method attome: the various governing equations related to CFD. dary condition & initial conditions. e Difference and Finite Volume methods in CFD model performance of fluid dynamics model. the various governing equations related to CFD. | ase change d, Enthalpy | 8 hours nterpolation problems; method. K2 K3 K3 K3 |
| function Differed CO1 CO2 CO3 CO4 CO5 Name 1 | ent approach Course Ou Understand Apply boun Apply Finit Evaluate the Understand of Authors Computati | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method atteme: the various governing equations related to CFD. dary condition & initial conditions. e Difference and Finite Volume methods in CFD model performance of fluid dynamics model. the various governing equations related to CFD. | ase change d, Enthalpy | 8 hours nterpolation problems; method. K2 K3 K3 K3 |
| function Differed CO1 CO2 CO3 CO4 CO5 Name 1 2 | ent approach Course Ou Understand Apply boun Apply Finit Evaluate the Understand Of Authors Computati Principles | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method ttome: the various governing equations related to CFD. dary condition & initial conditions. e Difference and Finite Volume methods in CFD model performance of fluid dynamics model. the various governing equations related to CFD. | ase change d, Enthalpy | 8 hours nterpolation problems method. K2 K3 K3 K3 |
| function Differed CO1 CO2 CO3 CO4 CO5 Name 1 | ent approach Course Ou Understand Apply boun Apply Finit Evaluate the Understand of Authors Computati Principles Radiative I | blems, Rayleigh-Ritz, Galerkin and Least square nd two-dimensional elements, Applications. Ph es for moving boundary; Variable time step method atteme: the various governing equations related to CFD. dary condition & initial conditions. e Difference and Finite Volume methods in CFD model performance of fluid dynamics model. the various governing equations related to CFD. | ase change d, Enthalpy | 8 hours nterpolation problems method. K2 K3 K3 K3 |

| | | M. TECH FIRST YEAR | | |
|--------|------------|---|------------------|----------------|
| Course | e Code | AMTME0215 | L T P | Credit |
| Course | | Advanced Mechanics of Solids | 300 | 3 |
| | objective: | | | |
| | <u> </u> | s students to | | |
| 2. | Solve adv | vanced solid mechanics problems using classica | al methods | |
| 3. | | nd behaviour of machine and structure under va | | conditions |
| 4. | | nd hardening rules and different elastic constant | Ų | |
| | | , anisotropic, hyper elastic and viscoelastic | | |
| 5. | Understa | nd boundary value problem which is applicable | e not only in so | olid mechanics |
| | | n heat transfer, fluid mechanics and acoustic di | | |
| 6. | | nd principle of virtual work and time dependen | | |
| 7. | | rse also aims at creation of an environment | | |
| | | ed to solve problems on advanced solid me | chanics and in | n this way to |
| | improve | their solving skills. | | |
| | | Course Contents / Syllabus | | |
| UNIT-I | | DUCTION | | 8 hours |
| | | minaries: Scalars, vectors and matrix variab | | |
| | | esian tensors and their algebra, coordinate tra | | |
| | | order tensors, elements of tensor calculus | | |
| | | s' and Green's), principal value theorem, ei | genvalues and | eigenvectors, |
| | | order tensor. | 1 > / / | |
| | | nation: Types of forces (point, surface and bo | | |
| | | Cauchy's relation and its proof, conserva | | |
| | | equilibrium equations, symmetry of stress to | | |
| | | and the associated planes, 3D Mohr's circl ctahedral planes, hydrostatic and deviatoric st | | |
| | | ors and their properties. | iess, mst and | second 1 lola- |
| UNIT-I | | matics of Deformation | | 0 1 |
| | | | | 8 hours |
| | | formation: Material and spatial co-ordinates | | |
| | | on; deformation and displacement gradients, C ny's small strain tensor and the rotation tensor, | | |
| | | and sign convention, principal strains and | | |
| | | aximum shear strain, volumetric strain, strain c | | |
| UNIT-I | | titutive Modelling | | 8 hours |
| | | ling: Thermodynamic principles, first and second | and law of the | |
| | | e's law for isotropic materials, elastic con | | |
| | | elastic and viscoelastic material models, st | | |
| | | plastic materials, flow and hardening rules. | | , constitutive |
| UNIT-I | | dary Value Problems | | 8 hours |
| | | Problems in Linear Elasticity: Field equation | s and bounda | |
| | | Beltrami-Michell stress compatibility condition | | |
| | | ain) and solution strategies. | s, 2D approxim | nations (plane |
| UNIT-V | | ational Principles in Solid Mechanics: | | 8 hours |
| | | les in Solid Mechanics: Elements of variation | nal calculus. e | |
| | | Lagrange equation and its application, type | | |
| | | l work, Principle of total potential energy as | | |
| | | d, time-dependent problems and Hamilton's pri | | |
| 6,,, | | | 1 | |

| | | Course Outcome: | | |
|-----|--|--|------------|--|
| CO | 1 | Students who successfully complete this course obtains advanced information on Advanced Mechanics of Solids and will be able to | K2 | |
| CO | 2 | Solve mechanics problem using matrix, vector and use element of tensor calculus. | K3 | |
| CO. | 3 | Learn about the elastic and plastic behaviour of material and evaluate stress invariants, principal stresses and their directions | K3 | |
| CO4 | 4 | Determine strain invariants, principal strains and their directions | K3 | |
| CO | CO5 Understand the theory of elasticity including strain/displacement, Hooke's law for isotropic material, elastic constants and their relationships | | | |
| Nar | ne of Au | thors/ Books / Publisher | | |
| 1 | | I.H., "Elasticity Theory Applications and Numerics", Elsevier Acaden | nic Press. | |
| 2 | Boresi, A.P., Sidebottom, O. M., "Advanced Mechanics of Materials", 5th Ed., John Wiley and Sons | | | |
| 3 | 2 | A.K., "Mechanics of Solids", PHI Learning Private Limited | | |
| 4 | Timoshenko, S.P., and Goodier, J.M., "Theory of Elasticity", 3rd Ed., McGraw Hill | | | |
| 5 | Srinath, L.S., "Advanced Mechanics of Solids", Tata McGraw Hill Education Private Limited | | | |
| 6 | 6 Fung, Y.C., "Foundations of Solid Mechanics", Prentice Hall Inc. | | | |

| M. TECH FIRST YEAR | | | | |
|--------------------|--|-----|--------|--|
| Course Code | AMTME0216 | LTP | Credit | |
| Course Title | Optimization Techniques | 300 | 3 | |
| Course Objectiv | es: The students should be able to | | · | |
| 1 | To introduce various optimization techniques i.e. classical, linea1programming, transportation problem, simplex algorithm, dynamiprogramming | | | |
| 2 | Constrained and unconstrained optimization tech optimizing an electrical and electronic engineering c real world situations. | - | - | |
| 3 | 3 To explain the concept of Dynamic programming and its applications to project implementation. | | | |
| 4 | 4 To introduce various Advanced optimization techniques i.e. integer an geometric programming, genetic algorithm and simulated annealing | | | |

UNIT – I Introduction

8 HOURS

Introduction and Classical Optimization Techniques: Statement of an Optimization problem, design vector, design constraints, constraint surface, objective function, objective function surfaces, classification of Optimization problems. Classical Optimization Techniques: Single variable Optimization, multi variable Optimization without constraints, necessary and sufficient conditions for minimum/maximum, multivariable Optimization with equality constraints. Solution by method of Lagrange multipliers, Multivariable Optimization with inequality constraints, Kuhn – Tucker conditions.

UNIT-II Linear Programming

8 HOURS

Linear Programming: Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm. Transportation Problem: Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems.

UNIT-III Unconstrained Nonlinear Programming

8 HOURS

Unconstrained Nonlinear Programming: One dimensional minimization. methods, Classification, Fibonacci method and Quadratic interpolation method Unconstrained Optimization Techniques: Univariant method, Powell's method and steepest descent method.

| UNIT-IV | Dynamic programming | 8 HOURS |
|---------|---------------------|---------|

Dynamic programming: Evolutionary algorithms: Genetic Algorithm, concepts of multiobjective optimization, Markov Process, Queuing Models

| UNIT-V | Advanced optimization techniques | 8 HOURS |
|--------|----------------------------------|---------|
|--------|----------------------------------|---------|

Advanced optimization techniques: integer and geometric programming, genetic algorithm, simulating annealing, optimization software's.

| Cour | rse Outcomes: The students would be able to | | | | |
|---------------|--|------------|--|--|--|
| CO | describe the need of optimization of engineering systems | K2 | | | |
| CO2 | 2 understand optimization of mechanical systems and formulate the optimization problems. | | | | |
| CO3 | apply classical optimization techniques, linear programming, simplex algorithm, transportation problem | К3 | | | |
| CO4 | apply unconstrained optimization and constrained non-linear programming and dynamic programming | K4 | | | |
| COS | Understand the advanced optimization techniques. | K3 | | | |
| 1 2 REF | Singiresu S. Rao, Engineering Optimization: Theory and Practice by John Wiley a 4th edition, 2009. H. S. Kasene& K. D. Kumar, Introductory Operations Research, Springer (India), I 2004 ERENCE BOOKS: | | | | |
| 4 | George Bernard Dantzig, Mukund Narain Thapa, "Linear programming", Springer operations research 3rd edition, 2003. | series in | | | |
| 5 | H.A. Taha, "Operations Research: An Introduction", 8th Edition, Pearson/Prent 2007. | tice Hall, | | | |
| 6 | Kalyanmoy Deb, "Optimization for Engineering Design – Algorithms and Examples", PHI Learning Pvt. Ltd, New Delhi, 2005. | | | | |
| | | | | | |

| | | M. TECH FIRST YEAR | | | | | |
|---|---|--|-------------|----------------|--|--|--|
| Cours | se Code | AMTME0217 | L T P | Credit | | | |
| Cours | se Title | Artificial Intelligence and Machine Learning (AIML) | 300 | 3 | | | |
| Cours | se object | tives: | | 1 | | | |
| 1 | 1 To introduce the basic concepts, theories and techniques of Artificial intelligence. | | | | | | |
| 2 | | luce basic concepts and applications of Machine learning | • | | | | |
| 3 | Help stud | lents to learn the application of AI / Machine learning | | | | | |
| | equisites | | | | | | |
| Studen | ts should | have basic knowledge computers, general engineering an | d mathema | atics. | | | |
| | | Course Contents / Syllabus | | | | | |
| UNIT | -I | FUNDAMENTALS OF AI | 8 | hours | | | |
| - Int | roduction | to AI, History of AI, Intelligent Systems, Types of Intelli | igence | | | | |
| _ ^ | A | and Research Areas of AI | | | | | |
| - Ag | ents and E | Environments | | | | | |
| UNIT | | SEARCH TECHNIQUES AND KNOWLEDGE REPRESENTATION | | hours | | | |
| | | Search, Types of search -BFS, DFS, Bidirectional Search | , Heurisitc | search - | | | |
| | | g, Beam Search Best First, A* search algorithm. Representation, Relational knowledge, Knowledge repres | entation as | logic | | | |
| | • | twork, Frame based knowledge. | | logic, | | | |
| UNIT | | SCOPE OF AI | 8 | hours | | | |
| - Na | tural Lang | uage Processing | | | | | |
| 1 4 | pert Syster | | | | | | |
| | zzy Logic | • | | | | | |
| | ural Netw | | 10 | | | | |
| UNIT | | INTRODUCTION TO MACHINE LEARNING | | hours | | | |
| | | to Machine learning systems. | | | | | |
| | · | earning, Unsupervised Learning and Deductive Learning ural Networks | 5. | | | | |
| UNIT | | Applications | 8 | hours | | | |
| - Im | age and fa | ce recognition, | | | | | |
| | ject recog | | | | | | |
| | | gnition besides Computer Vision, | | | | | |
| | | and Robotics | | | | | |
| Course outcome: After completion of this course students will be able to | | | | | | | |
| CO | Learr | the fundamentals of AI with engineering perspectives. | | K ₂ | | | |
| CO 2 | | rstand concept of knowledge representation and predi- ransform the real-life information in different representat | • | K ₂ | | | |
| CO 3 | | rstand state space and its searching strategies. | | K ₂ | | | |
| CO 4 | CO 4 Understand machine learning concepts and range of problems that can be handled by machine learning. | | | | | | |

| CO 5 | Understand the concepts of face, object, speech recognition and automation & robotics. | K ₂ |
|------------|--|----------------|
| Text & F | Reference books | |
| 1. Elaine | Rich, K. Knight, "Artificial Intelligence", 2/E, TMH, 1991. | |
| 2. Andre | w C., Staugaard Jr., Robotics and AI: "An Introduction to Applied Machine | |
| Intelli | gence", Prentice Hall ,1987. | |
| 3. S. Rus | ssell and P. Norvig, "Artificial Intelligence: A Modern Approach", 2/E, Pren | tice |
| Hall, 2 | 2003. | |
| 4. K. Boy | yer, L. Stark, H. Bunke, "Applications of AI, Machine Vision and Robotics" | ' World |
| Scient | ific Pub Co. , 1995. | |
| 5. I. Brat | ko, "Prolog Programming for Artificial Intelligence", 3/E, Addison-Wesley, | , 2001. |
| 6. C. M. | Bishop, "Pattern Recognition and Machine Learning", Springer, 2003. | |
| | | |

| | | M. TECH FIRST YEAR | | | | |
|-------|------------------|---|---------------------|---------------------------------|--|--|
| Cou | rse Code | AMTME0218 | LTP | Credit | | |
| | rse Title | Management Information System | 300 | 3 | | |
| | rse objecti | | | 1 | | |
| 1 | To make s | students Identify and understand the role o | f MIS in | business and | | |
| | management | | 1 1 4 11 1 | | | |
| 2 | ^ | roblems pertaining to conceptual information an | d detailing i | nformation of | | |
| 3 | a system des | udents Evaluate and differentiate various infor | motion avat | ame and their | | |
| 3 | economics. | ducents Evaluate and differentiate various infor | mation syste | enis and then | | |
| 4 | | Il be able to understand the strategic and pro | ect plannin | g and role of | | |
| • | | system in decision making. | eet plainin | g und role of | | |
| 5 | | udents integrate information system to ERP, a | nd other E | nterprise-wide | | |
| | | g-with ethics. | | 1 | | |
| Pre | | The student should have knowledge of Manufact | uring scienc | e | | |
| | | Course Contents / Syllabus | | | | |
| UN | IT-I Int | roduction to Flexible manufacturing sy | stem | 8 hours | | |
| Intro | oduction; Me | aning and definition of management information | n systems (N | MIS); Systems | | |
| | | MIS in facing increasing complexity in business a | | | | |
| | - | mation systems design;Problem Definition; s | •••• | | | |
| | ••• | n constraints; Determining information needs; | | • | | |
| | | ngalternative conceptual designs; Documenting the | ne conceptua | al designs. | | |
| | | ailing information systems design | | 8 hours | | |
| | | ation systems design; Informing and involving | | | | |
| mana | agement ofM | IS; Identifying dominant and tradeoff criteria; | Subsystem | definition and | | |
| sour | | | | | | |
| | | luation of information systems | | 8 hours | | |
| syste | ems;Productio | formation systems; Basic information system n and operations information systems; Market onsystem etc. | | | | |
| | | rmation systems for decision making | | 8 hours | | |
| | | ems for decision making; Programmed and no | n-nrogramn | ned decisions: | | |
| | | cision support systems, Strategic and project plan | | | | |
| UN | T-V Ent | erprise-wide information systems | | 8 hours | | |
| | | information systems; Integration with E | RP system | | | |
| | A | gration with external organizations; Virtu | • | zations; data | | |
| ware | housing; Da | ta mining; OLAP(Online Analytical Process | • | ms, Business | | |
| analy | ytics. Issues ir | ethics, crime, and security. | U / I | | | |
| Cou | irse outcom | e: After completion of this course student | ts will be ab | le to | | |
| CO | 1 Define N | IIS and its involvement in Business and Manager | nent | K ₂ , K ₃ | | |
| CO | | and define the problems related to design of information system. | conceptual | and K3 | | |
| CO | | Evaluate and differentiate various information system along with their K3 economics and utilization. | | | | |
| | ccononn | | | | | |
| CO | | and and implement information system for decision | on making. | K4 | | |

Text books& Reference Books

- 1. Management Information Systems O' Brien, J Tata McGraw Hill
- 2. Management Information Systems W.S. Jawedker Tata McGraw Hill
- 3. Management Information Systems S Sadagopan Prentice Hall of India
- 4. An Information System for Modern Management R.G. Mudrick Pearson
- 5. Management Information Systems M. Jaiswal Oxford University Press

| | | M. TECH FIRST YEAR | | |
|-------------------------------------|---|--|-------------------------|---|
| Course | Code | AMTME0219 | LTP | Credit |
| Course | | Flexible Manufacturing System | 300 | 3 |
| Course | objectiv | /e: | | |
| 1 | | vill learn the flexible manufacturing system. | | |
| 2 | Student v | vill learn the data-based management system. | | |
| 3 | | vill understand the group technology. | | |
| 4 | | vill learn the coordinate measuring machine tool. | | |
| 5 | | vill understand the material requirement planning system | l. | |
| Duo noo | nisitos | The student should have be eviled as of Manufacturin | | |
| rre-req | uisites: | The student should have knowledge of Manufacturir Course Contents / Syllabus | ig science | |
| UNIT-I | Int | roduction to Flexible manufacturing system | m | 8 hours |
| | | roduction to manufacturing system, different ty | | |
| technolog handling system: | gy, FMS system, F Computer | stem: Components of an FMS, types of system, work stations. Material handling and storage sys MS layout configuration, Material handling equipm function, FMS data file, system reports planning publication and have fite. | tem: Func nent. Comj | tions of the outer control |
| | | pplication and benefits. | | 0.1 |
| | _ | ibuted data processing in FMS processing in FMS: DBMS and their applications in | | 8 hours |
| data base | - Clampi | s in FMS –Integration of CAD and CAM - Part prog ng devices and fixtures data base. s – features of industrial robots - robot cell design an | | |
| UNIT-I | II Grou | ıp Technology | | 8 hours |
| coding s Determin Just In Ti | ystem, M ing the be me and L | y: Part families, part classification and coding. Typ achine cell design: The composite part concept, est machine arrangement, benefits of group technolo ean Production: Lean Production and Waste in Man automation, work involvement. | types of gy. | cell design. |
| UNIT-I | V Intro | oduction of FMS | | 8 hours |
| work cen specificat Applicati | tre and a ion and so on of s uring dat | mposition of FMS- hierarchy of computer control ssembly lines – FMS supervisory computer contro election – trends. imulation – model of FMS– simulation soft a systems – data flow – FMS database systems | ol – types ware – 1 | of software imitation – |
| UNIT-V | | luction Planning and control systems | | 8 hours |
| Production production control, | on Plann on schedu inventory n principle | ing and control systems: Aggregate Production Pl le, Material Requirements and Planning, capacity control, extensions of MRP CMM types: con es - programming and operation-in cycle gauging | v planning ntact and | , shop floor non-contact |
| CO 1 | | | | K ₂ , K ₃ |
| | Understa | and the components of flexible manufacturing system | .11 | K ₂ , K ₃ |
| CO 2 | | ne concept of data-based management system for i and CAM | ntegration | K3 |

| CO 3 | Understand the concept of part family formation and cell design.K3 | | | | |
|------|--|------|--|--|--|
| CO 4 | Understand the concept of automated material handling system | K4 | | | |
| CO 5 | CO 5 Understand the different module of MRP and CMM | | | | |
| Text | books& Reference Books | | | | |
| 1. | 1. Radhakrishnan P. and Subramanyan S., "CAD/CAM/CIM", Wiley Eastern Ltd., New | | | | |
| | Age International Ltd., 1994. | | | | |
| 2. | Raouf, A. and Ben-Daya, M., Editors, "Flexible manufacturing systems: | | | | |
| | recentdevelopment", Elsevier Science, 1995. | | | | |
| 3. | 3. Groover M.P., "Automation, Production Systems and Computer Integrated | | | | |
| | Manufacturing", Prentice Hall of India Pvt., New Delhi, 1996. | | | | |
| 4. | Kalpakjian, "Manufacturing Engineering and Technology", Addison-We | sley | | | |
| | Publishing Co., 1995. | | | | |

| | | M. TECH FIRST YEAR | | | | |
|--------------------------------------|-----------------------------|--|---|--|--|--|
| Cour | se Code | AMTME0220 L T P | Credit | | | |
| | se Title | Machine Vision 300 | 3 | | | |
| | se objectiv | | | | | |
| 1 | | the concepts of Physics behind Digital Image Processing. | | | | |
| 2 | | the Methods of Image Acquisition. | | | | |
| 3 | Ų | e different knowledge in different types image Processing. | | | | |
| 4 | | Developing knowledge of different types analysing the Captured Image. | | | | |
| 5 | Implementi | ng at the idea about Machine Vision Applications. | | | | |
| | | | | | | |
| | | Course Contents / Syllabus | | | | |
| UNIT | | NTRODUCTION | 8 hours | | | |
| Block Machin | Diagram an | Machine vision and Computer Vision – Benefits of Machin and Function of Machine Vision System Implementation of stem – Physics of Light – Interactions of Light – Refraction and s Equation. | of Industrial | | | |
| UNIT | -II I | MAGE ACQUISITION | 10 hours | | | |
| Specif Interfa Compu | cations and ce Architect | pes and Selection – Machine Vision Lenses and Opt Selection – Imaging Sensors – CCD and CMOS, Spec ures – Analog and Digital Cameras –Digital Camera Interface s, Specifications and Selection – Geometrical Image Formation. | eifications – es – Camera | | | |
| UNIT | -III I | MAGE PROCESSING | 8 hours | | | |
| | | oftware - Fundamentals of Digital Image - Image Acquisiti | | | | |
| | | in Spatial and Frequency Domain - Point Operation, T | | | | |
| - | | ng – Neighbourhood Operations, Image Smoothing and S | harpening – | | | |
| - | | Binary Morphology – Colour image processing. | 0.1 | | | |
| UNIT | | MAGE ANALYSIS – Region Features, Shape and Size Features – Texture | 8 hours | | | |
| | | g and Classification – 3D Machine Vision Techniques – Decision | | | | |
| UNIT | - | ACHINE VISION APPLICATIONS | 8 hours | | | |
| Machin Textile and S Survei | ne Vision A , Applicatio | Applications in Manufacturing, Electronics, Printing, Pha ns in Non-Visible Spectrum, Metrology, Vision Guided Robo ications – Agricultural, and Bio Medical Field, Augmen Metrics. | rmaceutical, otics – Field ted Reality, | | | |
| CO 1 | Explain | the concepts of Physics behind Digital Image Processing. | K3 | | | |
| CO 2 | Illustrate | the Methods of Image Acquisition. | K2 | | | |
| CO 3 | Apply th | e different knowledge in different types image Processing. | K3 | | | |
| CO 4 | 1 | knowledge of different types analysing the Captured Image. | K4 | | | |
| CO 5 | Impleme | nt at the idea about Machine Vision Applications. | K4 | | | |
| | | | | | | |

Text books

1. Alexander Horn berg, "Hand Book of Machine Vision", Wiley-VCH, 2006.

2. Davies E.R., "Machine Vision Theory, Algorithms and Practicalities", Elsevier, 2005.

Reference Books

1. NelloZuech, "Understanding and Applying Machine Vision", Marcel Decker, 2000.

2. Bruce Bachelor and Frederick Waltz, "Intelligent Machine Vision Techniques, Implementations and Applications", Springer-Verlag, 2001.

3. Rafael C. Gonzales, Richard. E. Woods and Steven L. Eddins, "Digital Image Processing Using MATLAB", McGraw Hill Education, 2014.

4. Milan Sonka, Vaclav Hlavac and Roger Boyle, "Image Processing, Analysis, and Machine Vision", Cengage Learning, 2014.

5. Malay K. Pakhira, "Digital Image Processing and Pattern Recognition", PHI Learning, 2011.

6. Chanda B. and Dutta Majumder D., "Digital Image Processing and Analysis", PHI Learning, 2011.

| M. TECH FIRST YEAR | | | | | | | |
|--------------------|---|--|----------------|--|--|--|--|
| Course | Code | AMTME0221 L T P | Credit | | | | |
| Course | | Rapid Manufacturing & Tooling 3 0 0 | 3 | | | | |
| Course | | | | | | | |
| 1 | Able to know the fundamentals of RP Systems & its evolution and the Process in RP and association of RP Systems with 3D modelling & Mesh | | | | | | |
| 2 | Able to know the RP Systems, Process, Materials & Classifications | | | | | | |
| 3 | Able to know and working with Mesh File & their formats like STL format, 3MF | | | | | | |
| | format, OBJ formats. Conversion to Mesh files, their properties, operations, | | | | | | |
| | storage, inspections & defects | | | | | | |
| 4 | Able to | know the applications of RP Systems in various Fields | | | | | |
| | | Course Contents / Syllabus | | | | | |
| UNIT-I | Ι | ntroduction: | 4 hours | | | | |
| | | oments, Fundamentals of RP Systems and its Classification | | | | | |
| | | otyping Process Chains, 3D Modelling and Mesh Gen | | | | | |
| Conversio | on and Tr | ansmission. | | | | | |
| UNIT-I | IF | RP Systems: | 12 hours | | | | |
| Liquid P | olymer H | Based Rapid Prototyping systems: SLA, Material Jetting, | Solid Input | | | | |
| | | apid Prototyping Systems: Laminated Object Manufacturing | | | | | |
| | | Modelling Systems, Power Based Rapid Prototyping Syste | ms: Selective | | | | |
| | - | ulti-Jet Fusion, Binder Jetting Systems. | 1 | | | | |
| UNIT-I | | RP Database & Design Optimization: | 8 hours | | | | |
| | | Data Formats, STL Format, STL file problems, STL file r | epair, DfAM, | | | | |
| | | ation, Gcode for RP Systems | | | | | |
| UNIT-I | | RP Applications: | 8 hours | | | | |
| | | ies for Moulding, RP Applications in developing prototypes | | | | | |
| | | dical fields, Development of bone replacements and tiss | ues, etc., RP | | | | |
| Course | | biological acceptability.e: After completion of this course students will be ab | le to | | | | |
| | outcom | et inter completion of this course students will be ub | | | | | |
| | involvem | nd the fundamentals of RP Technologies and process nent in them | K1,K2 | | | | |
| | Understand the methodology to manufacture the products using RP K3, K4 technologies and study their applications, advantages and case studies | | | | | | |
| CO 3 | Understand the Design aspects and their respective challenges along K3, K4, K5 with the resolution for them | | | | | | |
| CO 4 | Understand the various applications of various RP Systems with case K3,K4 studies & Materials | | | | | | |
| Text bo | oks | | 1 | | | | |
| | | ng: Principles an Applications: Chee Kai Chua, Kah Fai Leo | ong, Chu Sing | | | | |
| | ve Manuf | acturing Technologies: 3D Printing, Rapid Prototyping, and | Direct Digital | | | | |
| | | ent Stucker, David W. Rosen, Ian Gibson | 2 | | | | |
| Referen | - | | | | | | |
| - | | uring: The Technologies and Applications of Rapid Prototypi | ng and Rapid | | | | |
| Tooling | g: Pham, I | Duc, Dimov, S.S. | | | | | |

- 2. Rapid Prototyping and Manufacturing: Fundamentals of Stereo Lithography: P. Jacobs
- 3. Rapid System Prototyping with FPGAs: Accelerating the Design Process: R.C. Cofer, Benjamin F. Harding
- 4. Rapid Prototyping of Digital Systems: Hamblen, James O., Hall, Tyson S., Furman, Michael D.

| | | M. TECH FIRST YEAR | | | | |
|--|--|--|----------------|--|--|--|
| Course Code | | AMTME0222 L T | Р | Credit | | |
| Course Title | | Hybrid Vehicle Technology 3 0 | 0 | 3 | | |
| Course ob | | | | | | |
| | | stand working of Electric Vehicles and recent trends. | | | | |
| | | how & aptitude towards future trends in Hybrid Electric V | vehicle | s | | |
| | Understand the various energy storage devices | | | | | |
| | Understand the drive systems of hybrid vehicles | | | | | |
| | | stand energy management strategies | | | | |
| - | | 6, 6 6 | | | | |
| | | Course Contents / Syllabus | | | | |
| UNIT-I | Ι | ntroduction: | 4 | hours | | |
| and Electric | Driv | brid Electric Vehicles Conventional Vehicles. Hybrid E e-trains: Basic concept of electric traction, introduction gies, power flow control in electric drive-train topologi | to var | ious electric | | |
| UNIT-II | I | Electric Propulsion unit | | 12 hours | | |
| Electric Pro | opuls | ion unit: Introduction to electric components used in h | nybrid | and electric | | |
| vehicles, Co | onfigu | aration and control of DC Motor drives, Configuration | on and | control of | | |
| | | drives, configuration and control of Permanent Mag | | | | |
| - | | control of Switch Reluctance Motor drives, drive system | efficie | • | | |
| UNIT-III | | Energy Storage | | 8 hours | | |
| Vehicles. Ba | attery | : Introduction to Energy Storage Requirements in Hy , Fuel Cell, Super Capacitor and Flywheel based energy ation of different energy storage devices. | | | | |
| UNIT-IV | S | Sizing the drive system | | 8 hours | | |
| (ICE), Sizing | g the | system: Matching the electric machine and the internal propulsion motor, sizing the power electronics, selecting nunications, supporting sub systems. | | | | |
| UNIT-V | ŀ | Energy Management Strategies | | 8 hours | | |
| hybrid and comparison management | elect of d t strat | ment Strategies: Introduction to energy management tric vehicles, classification of different energy mana ifferent energy management strategies, implementation egies. Case Studies: Design of a Hybrid Electric Vehicle (fehicle (BEV). | gemen issue | gies used in t strategies, s of energy | | |
| Course ou | itcon | 1e: After completion of this course students will be | able t | 0 | | |
| | | op the electric propulsion unit and its control for ation of electric vehicles. | K1,K | 2 | | |
| (1) | Analyze different power converter topology used for electric K3, K4 vehicle application. | | | | | |
| CO 3 Io | dentif | y the principles of energy storage in hybrid vehicles | K3, K | 4, K5 | | |
| | Analyze the drive systems sizing. K3,K4 | | | | | |
| CO5 D | Develo | op the strategies for engine management. | K4 | | | |
| Text book | | | | | | |
| I CAL DUUK | | | | | | |

Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2003 Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004

Reference Books

James Larminie, John Lowry, Electric Vehicle Technology Explained, Wiley, 2003 Chris Mi, M. Abul Masrur, David Wenzhong Gao, Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives, John Wiley & Sons Ltd., 2011